



DOCUMENTATION ISG-kernel

Functional description Turning

Short Description:
FCT-S3

Preface

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Links below (DE)

<https://www.isg-stuttgart.de/produkte/softwareprodukte/isg-kernel/dokumente-und-downloads>

or (EN)

<https://www.isg-stuttgart.de/en/products/softwareproducts/isg-kernel/documents-and-downloads>

contains further information on messages generated in the NC kernel, online help, PLC libraries, tools, etc. in addition to the current documentation.

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This documentation uses the following icons next to the safety instruction and the associated text. Please read the (safety) instructions carefully and comply with them at all times.

Icons in explanatory text

- Indicates an action.
- ⇒ Indicates an action statement.



DANGER

Acute danger to life!

If you fail to comply with the safety instruction next to this icon, there is immediate danger to human life and health.



CAUTION

Personal injury and damage to machines!

If you fail to comply with the safety instruction next to this icon, it may result in personal injury or damage to machines.



Attention

Restriction or error

This icon describes restrictions or warns of errors.



Notice

Tips and other notes

This icon indicates information to assist in general understanding or to provide additional information.



Example

General example

Example that clarifies the text.



Programming Example

NC programming example

Programming example (complete NC program or program sequence) of the described function or NC command.



Release Note

Specific version information

Optional or restricted function. The availability of this function depends on the configuration and the scope of the version.

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1 Overview

Task

The CNC provides specific functions for turning work.

Possible applications

The following functions are available:

- Diameter programming
- Tool tip radius compensation (SRK)
- Thread cutting with endlessly rotating spindle (G33)
- Thread tapping without compensation chuck (G63, G331/G332)
- Feedrate per revolution (G95)
- Constant cutting speed (G96, G97, G196)
- Face and lateral surface machining (#CAX, #FACE, #CYL)

Programming

Refer to the appropriate sections for turning functions.

Parametrisation

Turning functions are configured by specific parameters which are described in the chapter Parameters [▶ 47].

Links to other documents

For the sake of clarity, links to other documents and parameters are abbreviated, e.g. [PROG] for the Programming Manual or P-AXIS-00001 for an axis parameter.

For technical reasons, these links only function in the Online Help (HTML5, CHM) but not in pdf files since pdfs do not support cross-linking.

2 Description

Turning is a manufacturing process in metal cutting and is regarded as one of the basic processes in mechanical metal cutting in addition to milling, drilling and grinding. The machine tool required for machining is the lathe. In its basic state, it consists of various components:

- a drive which rotates the workpiece fixed in the chuck
- a tool slide which bears the turning tool with handwheels and/or other drives to move the tool axes
- a stable and vibration-damping frame
- additional components, so-called bezels and a tailstock to support long turned parts

The simple mechanical shape of a universal lathe is depicted in the figure below. It is mainly used to produce small batches and manufacture one-off parts in workshops. For medium-size and large batch production, the so-called CNC lathe is used. It has a CNC controller which executes a programmed tool motion on complex paths.

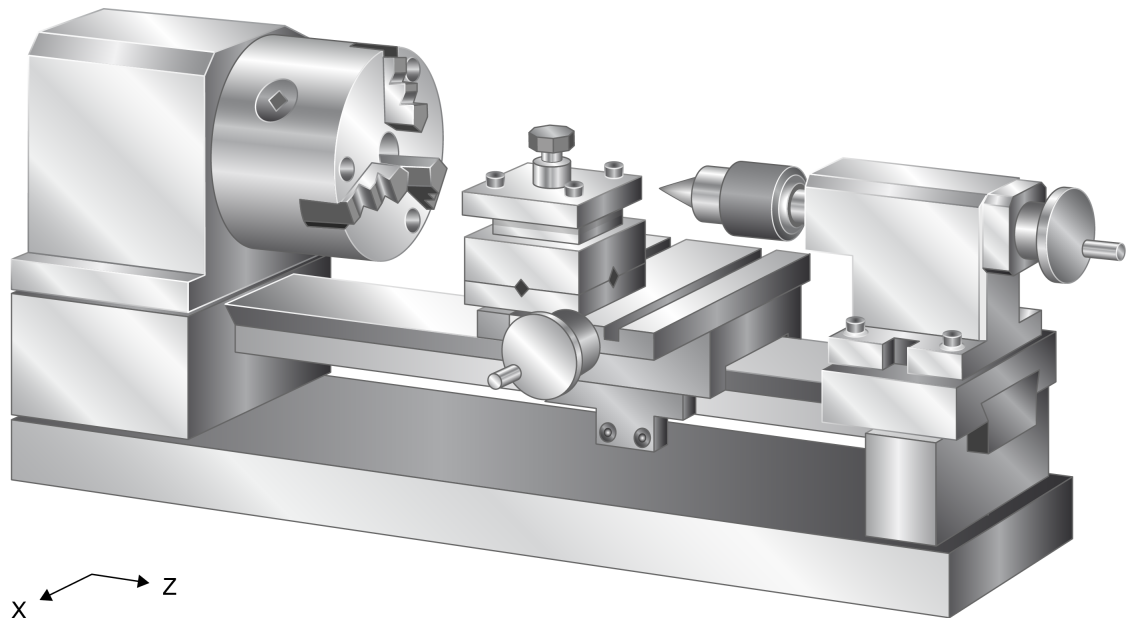


Fig. 1: Lathe

2.1 Standard turning functions

Standard turning functions are used for conventional turning work with an endlessly rotating spindle. A position-controlled interpolated CNC spindle axis must be configured as the main spindle to achieve the full scope of functions. For details see [FCT-S1].

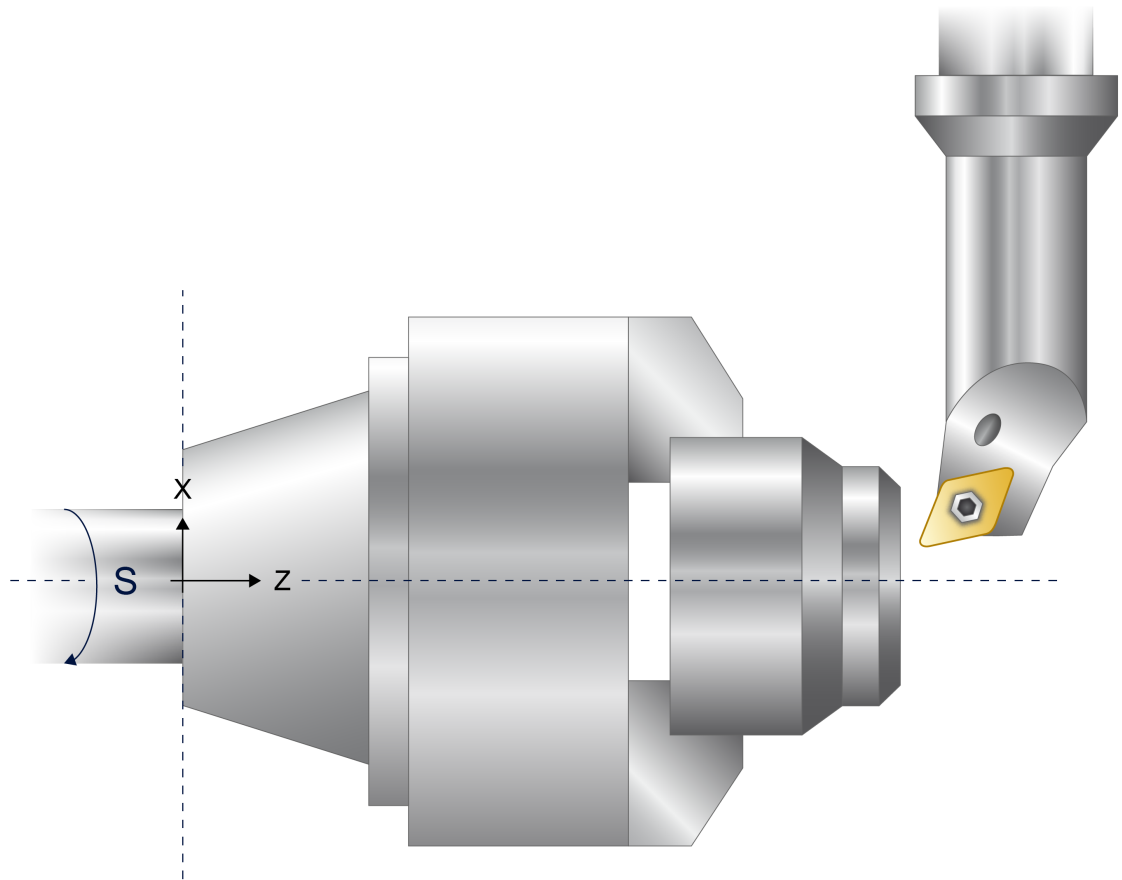


Fig. 2: Turning work

The tool-carrying spindle axis is commanded at the assigned speed by the spindle commands M03, M04 and M05.

A longitudinal and a face turning axis must be identified by an entry in the axis parameter P-AXIS-00015. The figure above shows an example where the Z axis is marked as the longitudinal turning axis (bit 0x80) and the X axis as the face turning axis (bit 0x40).

The conventional axis configuration consists of 3 Cartesian main axes in the order X-Y-Z (1st main axis, 2nd main axis, 3rd main axis). Machining is executed in the programmed G18 plane (Z, X).

Machining can also be executed in the default G17 plane. The alternative axis configuration must then be Z-X-Y.

Standard turning functions

| Function | Meaning | Unit |
|---|--|-------------------|
| G51 | Diameter programming | - |
| G52 | Deselect diameter programming | - |
| G41, G42 | Tool tip radius compensation, left/right | - |
| G40 | Deselect tool tip compensation | - |
| G95 | Feedrate per revolution | F [mm/rev] |
| G33 | Thread cutting | K [mm/rev] |
| G96 | Constant cutting speed | S [m/min] |
| G196 | Max. speed for G96 | S [1/min] |
| G94 | Default unit for path feed | F [mm/min] |
| G97/ | Default unit for spindle speed | S [1/min] |
| F: path feed S: spindle speed, cutting speed K: Pitch | | |

2.1.1 Diameter programming (G51/G52)

Syntax:

| | | |
|------------|-------------------------|----------------------|
| G51 | Select diameter value | modal |
| G52 | Deselect diameter value | modal, initial state |

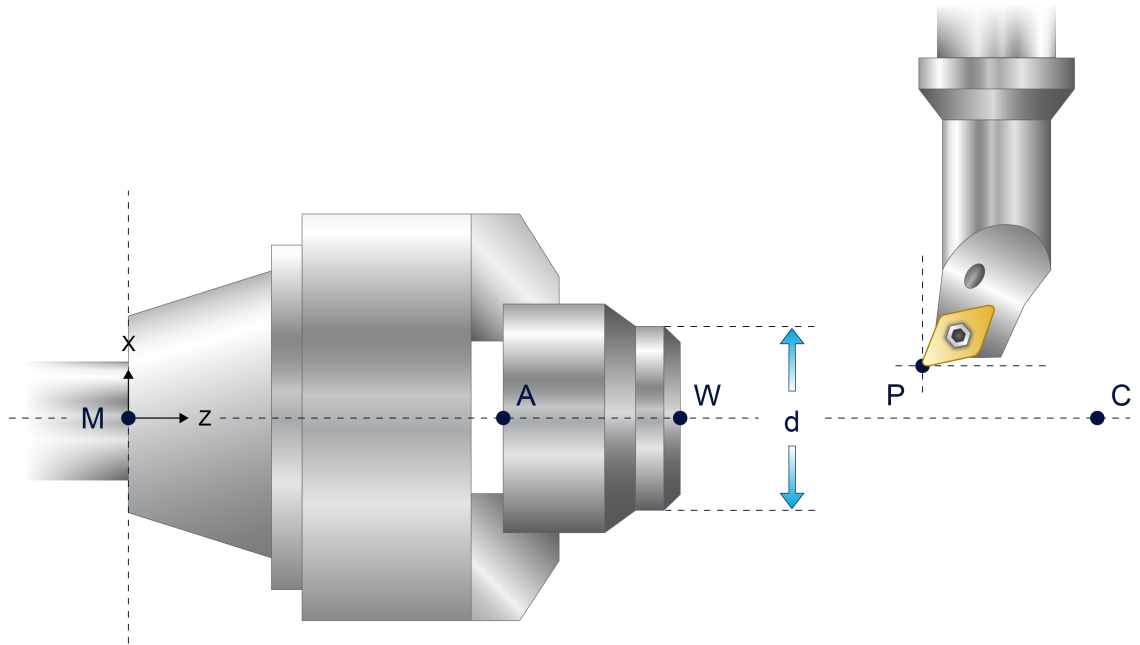


Fig. 3: Reference points and diameter programming

| | |
|------------------------|---|
| W Workpiece zero point | P Cutting point |
| X Face turning axis | Z Longitudinal turning axis |
| M Machine zero point | A Fixed stop point |
| C Control zero point | d Programmed dimension for diameter programming |

When diameter programming is selected, the positional values for the face turning axis in a motion block are interpreted as diameter values relative to the turning centre point.

It should be noted that the programmed coordinates of the face turning axis only correspond to the workpiece diameter if the zero point of the face turning axis is located at the turning centre point (irrespective of whether offsets act as a diameter; see Programming example).

The axis parameters can parameterise axes in "face turning" mode:

- G51 with absolute programming (G90) (P-AXIS-00058)
- ... and/or G51 with relative programming (G91) (P-AXIS-00059)
- Reference point programming (G92) and zero point programming (G53 – G59) in the diameter (P-CHAN-00091)

G51 acts on the axis which is operated in "face turning" mode. When the face turning axis is selected, the face turning axis must exist in the machining plane (G17, G18, G19).

The coordinates of the circle centre point (I, J, K) and circle radius programming (R) are not programmed in the diameter.

Diameter programming is deselected with G52.



Programing Example

Diameter programming (G51/G52) in G18

```
;General settings (optional):  
;Display position values in the diameter P-CHAN-00256 (TRUE, 1)  
  
;Settings of X axis:  
;Face turning axis, translatory: P-AXIS-00015 (0x41)  
;G51 with G90: P-AXIS-00058 (TRUE, 1)  
;G51 with G91: P-AXIS-00059 (FALSE, 0) (optional)  
;G92, G53-G59 in the diameter: P-CHAN-00091 (TRUE, 1) (optional)  
  
;Settings of Z axis:  
;Longitudinal turning axis, translatory: P-AXIS-00015 (0x81)  
;  
N05 G18  
N10 G90 G01 F1000  
N20 G51 X80 ;diameter 80 mm  
N30 G92 X10 ;G92 by 10 mm in the diameter  
N40 X0 ;position 0 + G92 => diameter 10 mm  
N50 G91 X50 ;X relative +50mm, in the diameter  
N80 G52 ;deselect diameter programming  
;...  
  
N90 M30
```

2.1.2 Cutter radius compensation (G40/G41/G42)

Syntax:

| | | |
|------------|----------------------|----------------------|
| G40 | Deselect CRC | modal, initial state |
| G41 | CRC left of contour | modal |
| G42 | CRC right of contour | modal |

Tool tip radius compensation (SRK) acts in the machining plane selected using G17, G18, G19 for turning work. In this plane, one of the axes must be operated in "face turning" mode and the other in "longitudinal turning" mode. (axis mode: P-AXIS-00015)

The data records stored in the D words are used as tool compensation values. For turning tools, the orientation of the cutter edge relative to the machining plane (face/longitudinal turning axis) must be specified in the parameter P-TOOL-00002 by an additional identifier 1...9 (see figure).

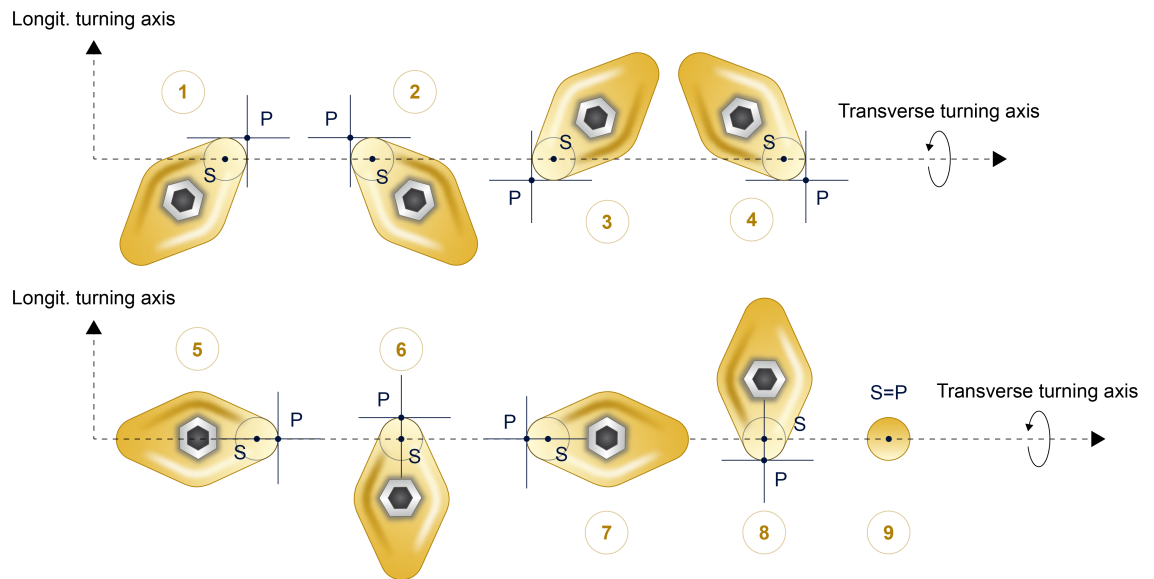


Fig. 4: Orientation of cutter edge to machining plane.

A typical turning tool is characterised by the following values/parameters:

- Tool type 1 (turning tool)
- SRK orientation 1...9
- Tool radius Tool tip radius
- Tool length --
- Tool offset (see figure below)

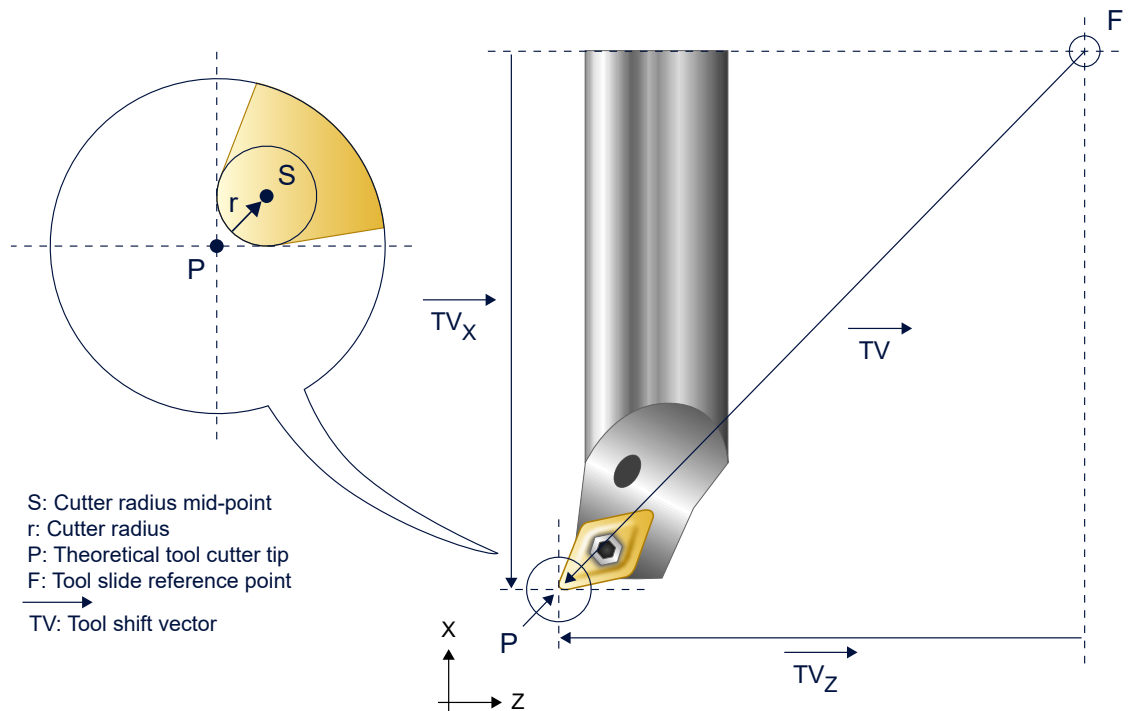


Fig. 5: Tool gauging for tool offset compensation.

When specifying tool axis offsets, their mathematical sign should be noted since it refers to components of the tool offset vector in the machining plane. In the example of a turning tool shown in the above figure, the offsets in the direction of the X and Y axis both have negative (mathematical) signs.

Tool offsets must be specified up to the theoretical tool top (point P).

A change between turning tool and milling tool is permitted when G41 or G42 is selected. With absolute programming (G90) the current axis offset values of the new tool are included in the calculation for the next motion block depending on the tool type.

2.1.3 2D cutter radius compensation (CRC) and 5-axis kinematics



Release Note

This function is available as of CNC Build V3.1.3081.2 or V3.1.3108.1.

This function allows 5-axis machines to also be used for conventional turn machining work. The driven milling tool is replaced by a fixed turning tool with a cutting insert. The kinematic ID identifies the related transformation as an element of the data set of kinematic parameters. The second rotary axis in the kinematic has no function in this application. It is replaced by a simulated axis and remains set to position 0. The physical C axis of the machine is commanded as a spindle and rotates the workpiece in continuous operation. The axis can therefore be configured as a spindle axis, for example, and be exchanged in coordinated motion for milling operation.

The basic axis and channel parameters required for using cutter radius compensation are described in [FCT-S3].

For use with a 5-axis kinematic, the channel parameter P-CHAN-00456 must also be set as follows:

```
trafo_mode          TOOL_TIP_RADIUS_COMP_IN_PLANE
```

2D CRC can be used in combination with kinematics.

The following kinematics support this function:

- KIN_TYP_57 – 5-axis kinematics with B/C workpiece table
- KIN_TYP_58 – Five-axis kinematics with A/C workpiece table

The tool can be oriented in relation to the workpiece at the CRC level, enabling more complex contours to be machined on the facing and longitudinal turning sides using a tool cutter edge position.

The CNC calculates CRC offsets depending on the orientation angle of the cutter edge in relation to the workpiece; the cutter edge is correctly guided during orientation motions.

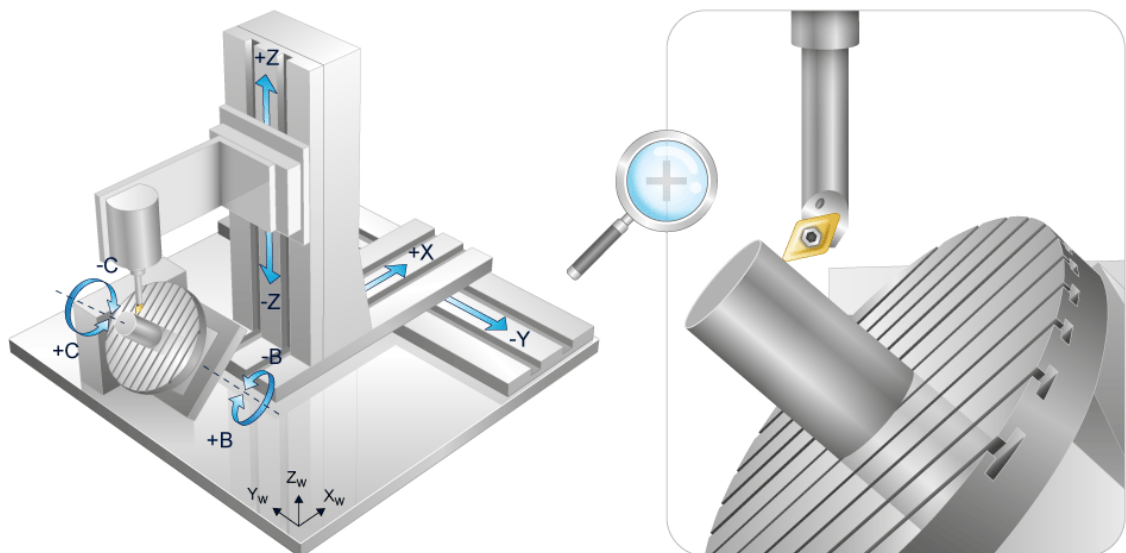
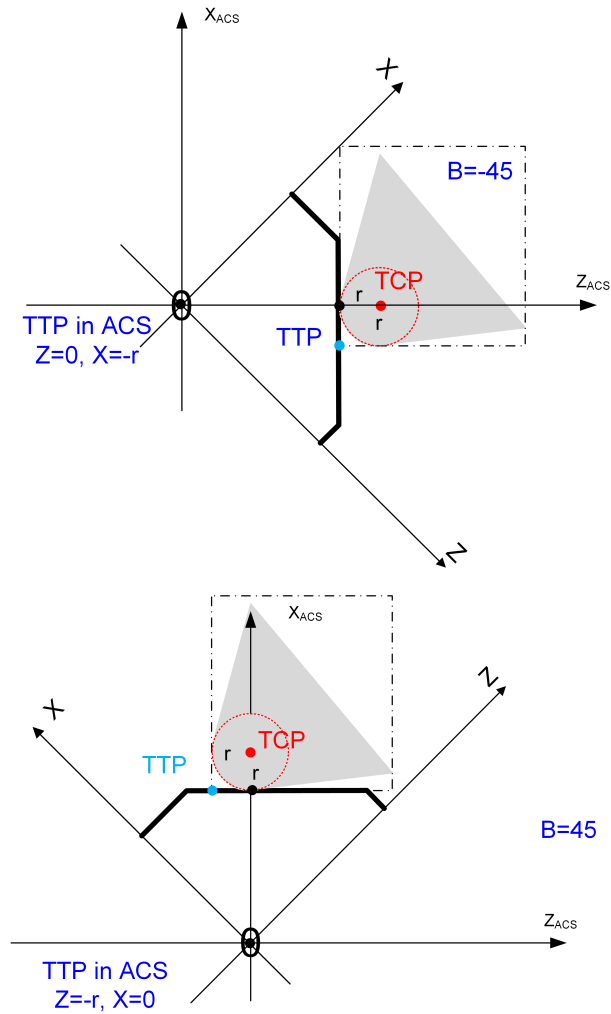


Fig. 6: Cutter radius compensation with kinematic 57

Position of the contact point depending on the orientation. The point designated by TTP denotes the tool tip point (Tool Tip Point).



Each contact point is also dependent on the cutter edge position of the turning tool. See Cutter radius compensation (G40/G41/G42) [► 12]



Programing Example

Cutter radius compensation with kinematic 57

```

%L SUB_MV_CUTTER_RADIUS_COMP
N1100 G51
N1200 G18
N1300 G41
N1400 G01 G90 X100 Z30 F2000
N1500          X60 Z50
N1600          Z90 B45
N1700          X100 Z110
N1800          Z140
N1900          B0
N2000          X60 Z160 B-45
N2100 G40
N2200 G90      X100 Z180 B0
M29

%main
N800 G01 G90 X0 Z200 F2000
N900 D1 ; -> CRC cutter edge position 3
N1000 M03 S500
N1100 #KIN ID[57]
N1200 #TRAFO ON
N1300 G90 B0
N1400 LL SUB_MV_CUTTER_RADIUS_COMP
N1500 #TRAFO OFF
M30
    
```

2.1.4 Feedrate per revolution (G95 / G94)

| | | |
|------------|---------------------------|---------|
| G95 | Feedrate in mm/revolution | (modal) |
| G94 | Feed in mm/min | (modal) |

When turning with active G95, a constant chip thickness can be defined using the F word in mm/rev, irrespective of the spindle speed (rpm) and provided that the path dynamics act with a limiting effect.

The CNC calculates the current path feed from the current command spindle speed and the programmed feedrate per revolution.

Here, the axis feedrate is linked to the rotational speed (rpm) of the position-controlled spindle. It is only valid in conjunction with the G function with which it was programmed. Therefore, if there is a change from G95 to G94 or G93, the F word valid for G95 is not adopted.

Example: S: 1200 rpm, F: 1.5mm/rev -> VB = 1800mm/min



Programing Example

Feedrate per revolution


```
N10 F1000 X100 M3 S1200 ;feedrate 1000 mm/min G94
N20 G95 F1.5 ;feedrate 1.5 mm/rev, spindle speed 1200 rpm)
N30 G94 X50 ;feedrate 1000 mm/min valid from N10
N40 G93 F20 X20 ;machining time 20 s
N50 G95 Y200 S2000 ;feedrate 1.5 mm/rev valid from N20;
;spindle speed 2000 1/min)
N60 M30
```

2.1.5 Thread cutting with endlessly rotating spindle (G33)

Single-start/multi-start threads

When thread cutting with an endlessly rotating spindle (G33), the path motion is synchronised to the zero passage of the spindle rotation. Therefore, the thread can also be cut in several passes in succession. When an offset angle is specified as option, multi-start threads can also be produced.

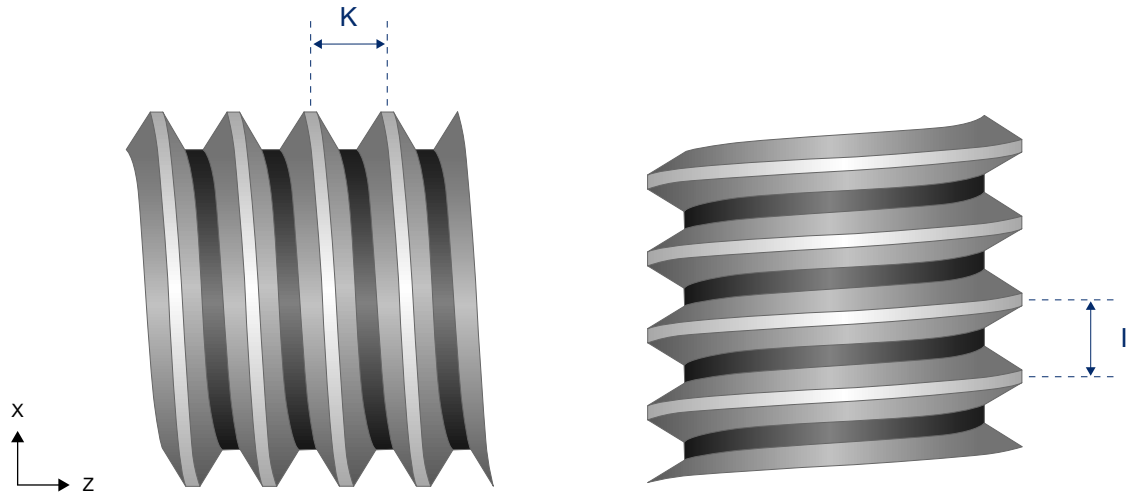
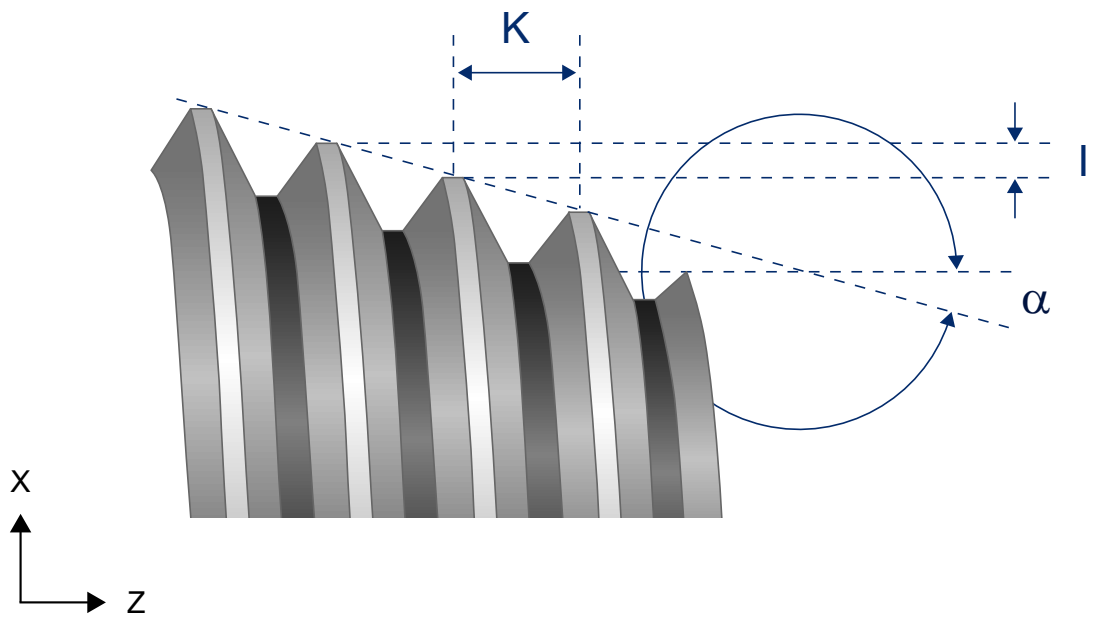
To achieve a good machining result and to minimise path errors, feedforward control can be selected for the spindle and for path axes.

Programming

Syntax example for ZX plane (longitudinal axis Z, feed axis X):

G33 Z.. K.. [<spindle_name>.OFFSET=..] modal

| | |
|--------------------------|--|
| G33 | Thread cutting with endlessly rotating spindle. The G33 function is modal. The next motion block with a modal block type (G00, G01, G02, G03, spline, polynomial) deselects thread cutting. |
| Z.. | Target point ("thread length") in [mm, inch] |
| K.. | The thread pitch is programmed with active thread cutting in the unit [mm/rev, inch/rev] without a mathematical sign using the address letters I, J and K. They are assigned to the X, Y and Z axes according to DIN 66025. The thread pitch is modal up to program end and should not be zero on when G33 is selected. The feed is not programmed using the F word but results from the spindle speed and the thread pitch. The pitch of longitudinal or tapered threads at an inclination angle less than 45° is specified by the address letter K if the Z axis is the longitudinal turning axis. With facing or tapered threads with a pitch greater than or equal to 45°, the pitch is specified by I if the X axis is used as the face turning axis, and by J if the Y axis is used. The figure below shows examples for specifying thread pitch using the address letters in the Z-X plane. |
| <spindle_name>.OFFSET=.. | Thread offset angle in [°] in spindle modulo range. Only required as an option for multi-turn threads. The offset angle is modal up to program end. Spindle name according to P-CHAN-00053. The "=" character is optional. |

Pitch values I, K with longitudinal thread

Fig. 7: Value of thread pitch for longitudinal thread
Pitch values I, K with tapered thread

Fig. 8: Value of thread pitch for tapered thread



Programming Example

Thread cutting with endlessly rotating spindle (G33)

G33 Z.. K.. [S.OFFSET=..]

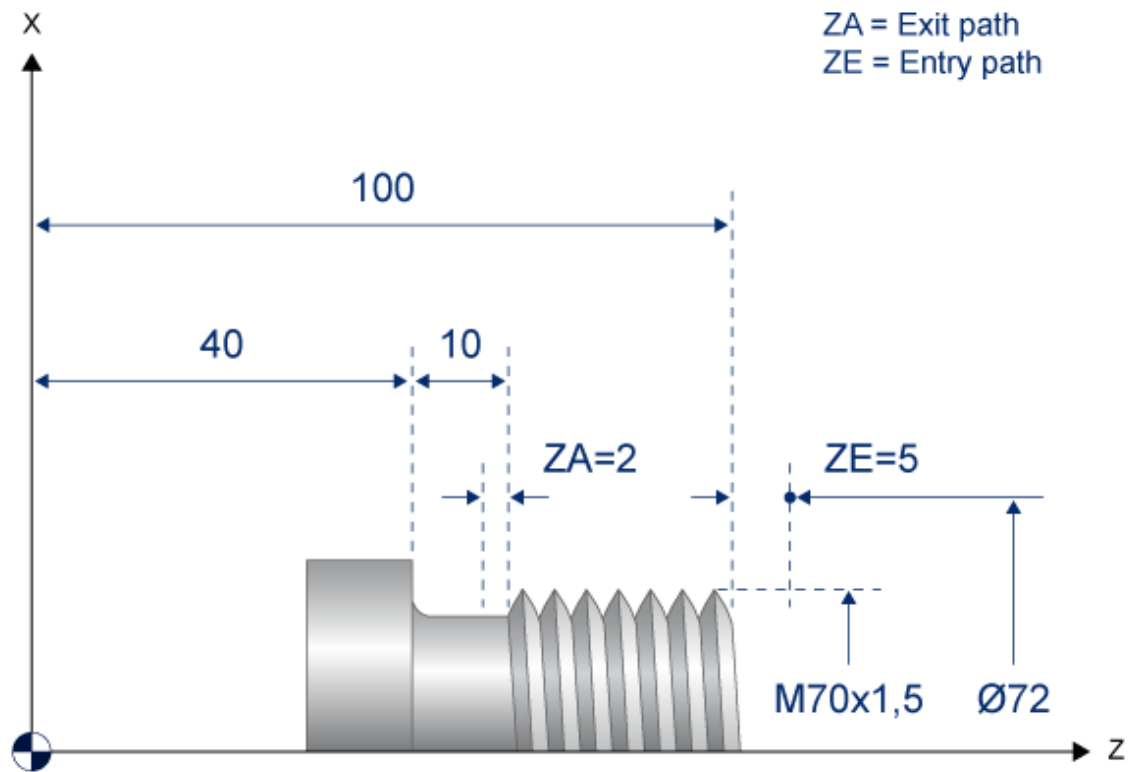


Fig. 9: Representation of geometry example

Cutting a longitudinal thread (M70x1.5) with several cuts:

```
%L longit_thread

N100 G33 Z48 K1.5 ;Cut thread turn
N110 G00 X72 ;Retract and move
N120 Z105 ;to start position
N130 M29 ;Subroutine end

%G33 (thread depth 0.92 mm)
N10 G51 ;Select diameter programming
N15 T1 D1 M03 S400 ;Select tool, start spindle
N20 G00 X72 Z105 ;Approach

N25 G01 X69.54 F1000 ;Position at 1st cutting depth
N30 LL longitudinal thread ;1st thread cut

N35 G01 X69.08 ;Position at 2nd cutting depth
N30 LL longitudinal thread ;2nd thread cut

N35 G01 X68.62 ;Position at 3rd cutting depth
N30 LL longitudinal thread ;3rd thread cut

N35 G01 X68.16 ;Position at final depth
N30 LL longitudinal thread ;4th thread cut

N35 G01 X68.16 ;Reposition at final depth
N30 LL longitudinal thread ;Empty cut

N60 M05 X150 Z200 ;Moving to end position
N65 M30 ;Program end
```

Cut a 2-turn longitudinal thread (M70x1.5)

```
%G33_2 (2-turn thread, thread depth 0.92 mm)
N10 G51 ;Select diameter programming
N15 T1 D1 M03 S40 ;Select tool, start spindle
N20 G00 X72 Z105 ;Approach
N25 G01 X68.16 F1000 ;Position at thread depth
N30 G33 Z48 K1.5 ;Cut 1st thread turn
N35 G00 X72 ;Retract and move
N40 Z105 ;to next
N45 G01 X68.16 ;start position
N50 G33 Z48 K1.5 S.OFFSET=180 ;Cut 2nd thread turn at 180°
N55 G00 X72 ;Retract and move
N60 M05 X150 Z200 ;to end position
N65 M30 ;Program end
```

Cutting a tapered thread

```
%L tapered thread
N010 G33 Z90 X1 I5.0           ;Cut thread turn (reference I)
; N010 G33 Z90 X1 K5.0       ;Cut thread turn (reference K)
N020 G00 X72                 ;Retract and move
N030 Z105                   ;to start position
N040 M29                     ;Subroutine end

%G33
N050 G00 X0 Y0 Z0
N060 G18
N070 G51                     ;Select diameter programming
N080 D1 M03 S1               ;Select tool, start spindle
N090 G00 X105 Z105          ;Start
N100 G01 X100 F1000         ;Position at 1st cutting depth
N110 LL tapered thread      ;1st thread cut
N120 M05 X150 Z200         ;Move to end position
N130 M30                     ;Program end
```

2.1.6 Thread cutting at actual spindle speed

When cutting a thread, the spindle speed may tend to deviate under load. In order to execute thread tapping in such cases, the motion of the linear axes can be directly coupled to the spindle's actual speed. This means that a path motion is also synchronised to the zero passage of the actual positions.

To avoid set value jumps in path axes, a very noisy actual spindle speed can be smoothed by an averaging filter.



Release Note

Function available as of V3.01.3080.16.

The function is activated either with P-CHAN-00834 or with the NC command #TURN [THREAD_CUT_ACT_SPEED=1 ...].



Example

Thread cutting at actual spindle speed]

Define in channel parameters:

```
thread_cutting.use_actual_speed 1 ( P-CHAN-00834)
thread_cutting.n_cycles          5 ( P-CHAN-00835)
```

Alternative definition in NC program:

```
#TURN[THREAD_CUT_ACT_SPEED=1 THREAD_CUT_N_CYCLES=5]
```



Programing Example

Thread cutting at actual spindle speed

```
%spindle_test.nc
(Thread cutting at actual speed)
N15 M03 S40           ; Start spindle
N20 G00 X72 Z105     ; Approach
N25 G01 X68.16 F1000 ; Position at thread depth
N30 G33 Z48 K1.5     ; 1. Cut thread turn at command speed
N35 G00 X72         ; Retract
N40 Z105            ; and move
N45 G01 X68.16     ; to next start position

; Thread cutting at actual speed and filtered values
N50 #TURN[THREAD_CUT_ACT_SPEED=1 THREAD_CUT_N_CYCLES=20]
; 2. Cut thread turn at 180° at actual speed
N55 G33 Z10 K1.5 S.OFFSET=180

N60 G00 X72         ; Retract and move
N65 M05 X150 Z200  ; to end position
N70 M30
```

2.1.7 Constant cutting speed (G96/G97/G196)

Syntax:

| | | |
|-------------|---|------------------------------------|
| G96 | Selecting constant cutting speed | modal |
| G97 | Deselecting constant cutting speed, selecting spindle speed | modal, initial state |
| G196 | Maximum spindle speed for G96 | G196 non modal max. speed modal |

Using the G functions G96, G97 and G196, it is possible to optionally change the interpretation of the S word:

| | |
|------|--|
| G96 | S in [m/min or ft/min *] (cutting speed) |
| G97 | S in [rpm] (spindle speed) |
| G196 | S in [rpm] (max. spindle speed during G96) |

* [as of Build V2.11.2032.08 with G70 and P-CHAN-00360 = 1]

When selected with G96, the starting rpm of the spindle is calculated from the programmed cutting speed and the distance of the tool tip to the turning centre point. This distance results from the last (not in the current NC block) programmed position and the reference point offset of the face turning axis. Exactly one face turning axis must be present in the current machining plane (G17, G18, G19).

A cutting speed programmed for G96 using the S word is only valid until it is deselected by G97. With G96, constant cutting speed is only activated when the S word is programmed.

Specifying a maximum spindle speed with G196 in conjunction with the S word is optional and only active during G96. Spindle speed limiting must be programmed before G96 is selected.

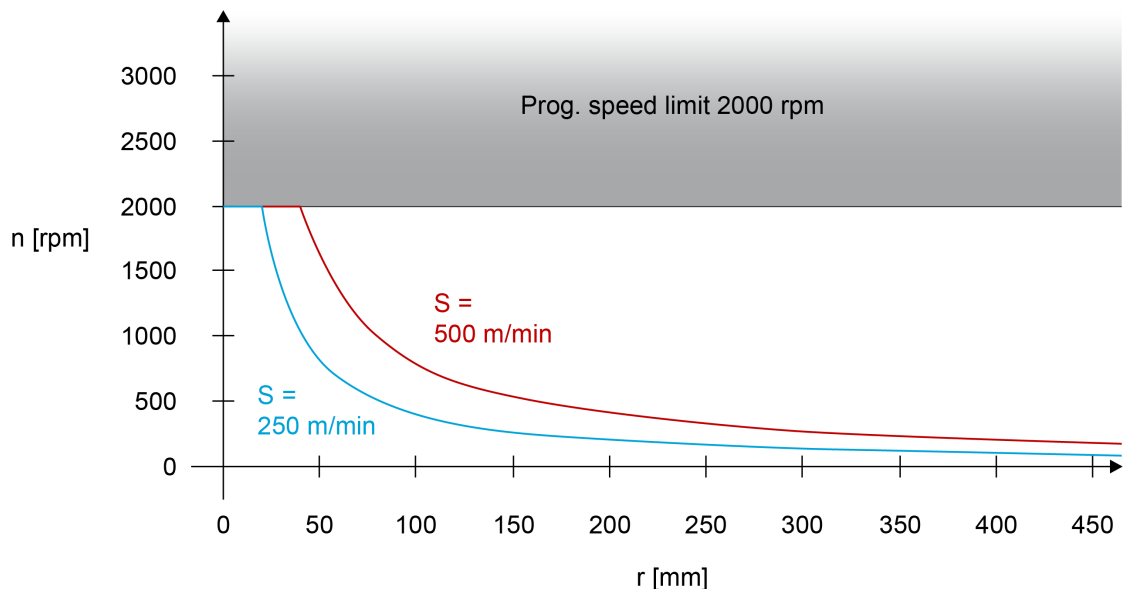


Fig. 10: Spindle speed with active G96



Release Note

Extended G function G196

As of Build V3.1.3057.04

Alternatively, the maximum spindle speed can be programmed as an additional value in [rpm] in conjunction with G196. It is modal.

This syntax permits the programming of G196 and G96 in the same NC block. A separate specific NC block is not required.

Syntax:

G196 = <Max_spindle_speed>

G196 non modal,
max. speed modal

Close to the turning centre point, the programmed maximum spindle speed (G196) or the maximum spindle speed specified in the assigned axis parameters P-AXIS-00212 defines the limits of the constant cutting speed.

When deselected with G97, the last spindle speed set is retained.

Motion blocks of the face turning axis in rapid traverse (G00) lead to an interruption of G96 to prevent undesired speed value changes when the tool is positioned. The next motion block with G01, G02 or G03 cancels suppression of G96.



Programing Example

Constant cutting speed (G96/G97/G196)

```
; X is the face turning axis

N10 M03 S1000 G01 F1500 X100
N20 G196 S6000 ;max. speed 6000 rpm
N30 G96 S63 ;select const. cutting speed 63 m/min,
           ;workpiece radius 100mm corresp. to X coordinates
N40 X80
N50 S4 X50 ;new cutting speed 4m/min; workpiece radius 80mm,
           ;at block end 50mm
N60 G97 ;max. speed 6000 rpm not effective here!
N80 G92 X-10 ;reference point offset in X by -10mm
N90 G96 X60 ;cutting speed from N50 not valid: const.
           ;cutting speed not active, speed 8000 rpm
N100 S25 X70 ;cutting speed 25m/min, workpiece radius 50mm,
            ;(=60mm+BPV), const. cutting speed active
N110 G00 X450 ;rapid traverse: speed remains constant
N115 X70
N120 G01 X40 ;suppress G96 cancelled
N110 M30
```

2.1.8 Constant cutting speed at feedrate per revolution (G96, G95)

When combined with the functions G96 and G95, a constant chip thickness and constant cutting speed (*) are obtained. The path feed is adapted to the spindle speed. When face turning, the following path speed curve results depending on the X position (turning radius). The path feed increases towards the turning centre point.

(*) Provided the dynamics of the spindle and path do not result in limiting effects.

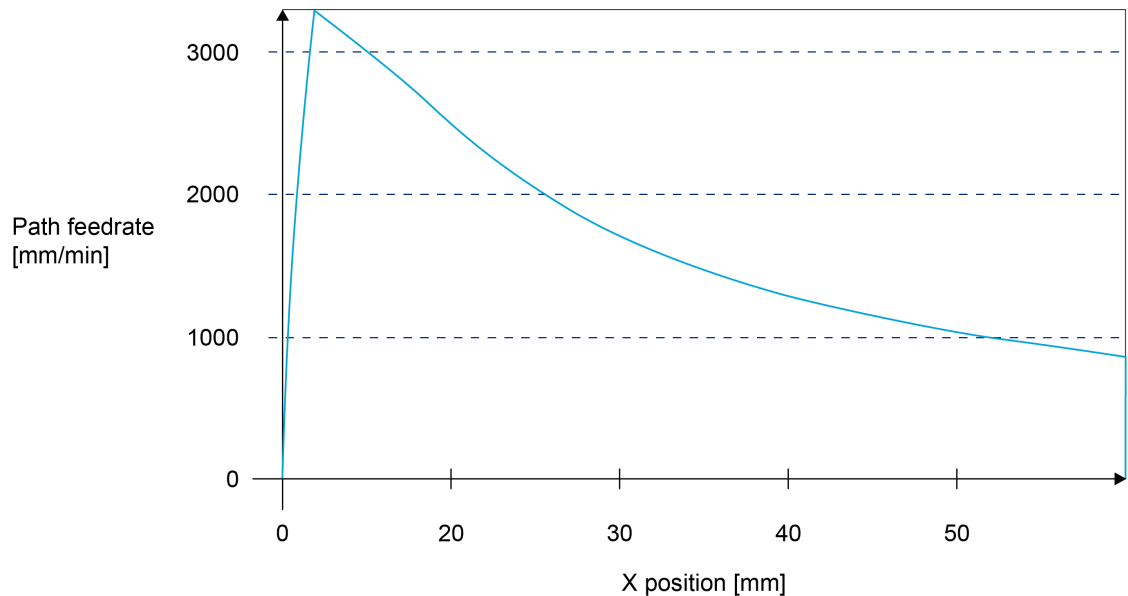


Fig. 11: Path feed for G96 at G95



Programing Example

Constant cutting speed at feedrate per revolution

```

; X... Face turning axis

N10 M03 S2000 G01 X60 Z100 F1500
N20 G196 S2500           ;max. Speed 2500 1/min
N25 G95 F1.5             ;feedrate per revolution 1.5mm/rev
N30 G96 S100           ;const. cutting speed 100m/min
N40 Z49
N50 X10
N60 G00 Z50
N70   X60                ;rapid traverse: speed remains constant
N80   Z48
N90 G01 X10              ;suppress G96 cancelled
N100 G97                ;Deselect const. cutting speed
N110 G94                 ;deselect feedrate per revolution
N120 M30
  
```

2.1.9 Tapping (G331/ G332)



Release Note

This function is available as of CNC Build V3.1.3067.01.

Syntax example of tapping in Z direction:

| | | | |
|-------------|---|-------------------------|-------|
| G331 | Z.. K.. <spindle_name>.. | Thread tapping | modal |
| G332 | Z.. [K..] [<spindle_name>..] | Thread tapping, retract | modal |

| | |
|------------------|--|
| G331 | Thread tapping |
| Z.. | Thread depth (target point) in the tapping axis in [mm, inch] |
| K.. | Thread pitch in assigned interpolation parameter in [mm/rev, inch/rev] |
| <spindle_name>.. | Spindle speed consisting of spindle name according to P-CHAN-00053 and speed value in [rpm] |
| G332 | Retract from threaded bore (Retract). G332 causes an automatic direction reversal of the spindle on retraction. |
| Z.. | Retract position of tapping axis after tapping in [mm, inch] |
| K.. | Thread pitch in assigned interpolation parameter in [mm/rev, inch/rev]. The thread pitch must be the same pitch as used for the threaded bore assigned in G331. The parameter is optional. If not programmed, the pitch in block G331 applies. |
| <spindle_name>.. | Spindle speed consisting of spindle name according to P-CHAN-00053 and speed value in [rpm]. The parameter is optional. If not programmed, the speed in block G331 applies. |

This type of tapping (G331/ G332) requires a position-controlled spindle which is tracked by the CNC synchronous to the path motion. In this case the spindle and the feed motion of the participating axes are matched precisely and dynamically. A compensatory chuck is not required.

The thread type is defined by specifying a sign for thread pitch.

- Pitch without or with positive sign (+): Right-hand thread, e.g. K2 or K+2
- Pitch with negative sign (-): Left-hand thread, e.g. K-2

The thread tapping axis feedrate is a product of the programmed pitch and the spindle speed. The permissible speed limits apply to the internal calculation. An error message is output if these limits are violated.

The feed rate continues to apply after tapping is completed. With the following G331/G332, the feedrate is again calculated from the related programmed or saved values of pitch and spindle speed.

G331/G332 is deselected by selecting a different modal block type (e.g. linear motion G01) and the spindles are released from the coordinated motion. A non-modal block type (e.g. dwell time with G04) does not deactivate G331/ G332.

An error message is output if the pitch or spindle speed with G331/G332 are equal to zero or the tapping axis and pitch parameters fail to match. Valid combinations are X with I, Y with J and Z with K.

M03, M04, M05, M19 cannot be programmed in combination with G331/G332.



Attention

The spindle (or the thread tapping drill) must be at standstill when G331 is selected. This can be achieved by previously programming M05 (Stop spindle) or M19 with S.POS (Position spindle).



Programming Example

Tapping (G331/ G332)

Tap right-hand thread with pitch 2 mm, thread depth 50 mm, spindle speed S 200 rpm, Z is tapping axis:

```
;/...
G01 F2000 G90 X0 Y0 Z0 ; position axes
M19 S.POS=0 M3 S100 ; stop and position spindle
;/...
G331 Z-50 K2 S200 ; tap in Z
G332 Z10 K2 S200 ; retract
G01 F1000 X50 ; reposition, deselect tapping
G331 Z-50 K2 S200 ; tap in Z
G332 Z10 K2 S400 ; retract at increased speed
G01 F1000 X100 ; reposition, deselect tapping
G331 Z-50 K2 S200 ; tap in Z
G332 Z10 ; retract, K and S from G331
G01 F1000 X150 ; reposition, deselect tapping
;/...
```

Tap right-hand thread with pitch 1.5 mm, thread depth 60 mm, spindle speed S 150 rpm, X is tapping axis:

```
;/...
G01 F2000 G90 X100 Y0 Z0 ; position axes
M19 S.POS=0 M3 S100 ; stop and position spindle
;/...
G331 X40 I1.5 S150 ; tap in X
G332 X110 I1.5 S150 ; retract
:
```



Programing Example

Tap at relative speed

```
%Tap at relative speed

N010 G91 G19 G0 X100 M03 S2000
N020 S2[MC_GearIn Master=S1 \ ; couple tool
RN=1 RD=1 Mode=256 \ ; spindle S2 to the
PhaseShift=1800000 WAIT_SYN] ; main spindle S1

N030 #MAIN SPINDLE[S2] ; main spindle tool spindle S2
N040 G331 Z-100 K1.5 S200 ; tap right-hand thread
N050 G332 Z100 K1.5 S200 ; retract from threaded bore
N060 G01 X300 F1000
N070 S2[MC_GearOut WAIT_SYN] ; release coupling to main spindle
N080 #MAIN SPINDLE[S1]
N090 M30
```

2.1.10 Thread drilling without compensating chuck (G63)

Syntax example of tapping in Z direction:

G63 Z.. F.. <spindle_name>.. modal

| | |
|------------------|---|
| G63 | Thread tapping |
| Z.. | Thread depth (target point) in the tapping axis in [mm, inch] |
| F.. | Feed rate in [mm/min, m/min, inch/min] |
| <spindle_name>.. | Spindle speed consisting of spindle name according to P-CHAN-00053 and speed value in [rpm] |

With this kind of tapping (G63) the position-controlled spindle is tracked by the CNC synchronously to the path motion. In this case the spindle and the feed motion of the participating axes are matched precisely and dynamically. A compensatory chuck is not required. The programmed feed rate must match the programmed spindle speed and the thread pitch and is calculated as follows:

Feed rate F [mm/min] = speed S [rpm] * pitch [mm/rev]

G63 is deselected by the selecting a different modal block type (e.g. linear motion G01). A non-modal block type (e.g. dwell time with G04) does not deactivate G63.

The path feed rate (F word) and spindle speed (S word) do not necessarily need to be specified in the same NC block as G63. The feed rate calculation must always be based on the last values programmed.

An error message is output if the path feed rate or spindle speed are equal to zero with G63 is selected.

M03, M04, M05, M19 cannot be programmed in combination with G331/G332.



Attention

The spindle (or the thread tapping drill) must be at standstill when G63 is selected. This can be achieved by previously programming M05 (Stop spindle) or M19 with S.POS (Position spindle).

Cutting a left-hand thread or movement out of a thread hole is programmed with a **negative S value**.

In C axis mode, the gear stage can be defined using the parameter P-AXIS-00052.



Programing Example

Tapping (G63)

Tap a right-hand thread with pitch 1.25 mm, thread depth 50 mm. At a programmed spindle speed S of 200 rpm the calculated feedrate is:

$$F = 200 * 1.25 = 250 \text{ mm/min}$$

```
;...
G01 F2000 G90 X0 Y0 Z0 ; position axes
M19 S.POS=0 M3 S100 ; stop and position spindle
;...
G63 Z-50 F250 S200 ; tap
      Z0 S-200 ; retract from threaded bore
G01 F1000 X100 ; reposition, deselect tapping
:
```



Programing Example

Tapping (G63)

```
%Tapping_G63

N05 X0 Y0 Z0
N10 G91 Z100
N20 M19 S.POS180 M3 S100 ; position spindle

N30 G63 Z-50 F300 S200 ; tap
N40 Z100 S-200 ; retract from threaded bore

N50 G01 X200 F3000 ; reposition, deselect tapping

N60 G63 Z-70 F300 S200 ; tap
N70 Z100 S-200 ; retract from threaded bore

N80 M05 G01 X300 F1000
N90 M30
```

A thread can also be executed in a rotating workpiece using G63 or G331/G332. The thread tapping drill feedrate results from the speed difference between the tool spindle and the driven thread tapping drill. Before starting the actual tapping, the spindle with the thread tapping drill must be coupled to the workpiece spindle at a synchronous speed. No spindle stop is required to start tapping or to establish the speed coupling. The process can be started on the fly both for the tool and the workpiece spindles.

2.1.11 Thread tapping with spindle actual positions

When tapping a thread, the spindle speed may tend to deviate under load. In order to execute thread tapping in such cases, the movement of the linear axes can be directly coupled to the spindle's actual positions.



Release Note

This function is available as of Build V3.01.3080.04.

The function is activated either with P-CHAN-00761 [▶ 48] or with the NC command #TURN[TAPPING_ACT_POS=1 ...]



Example

Thread tapping with spindle actual positions

Set the following parameters:

| | | |
|-----------------------------|---|------------------|
| tapping.use_actual_position | 1 | (P-CHAN-00761) |
| tapping.n_cycles | 5 | (P-CHAN-00762) |

NC program

```
%tapping.nc
; tapping command speed S=200rpm,
; right-hand thread with 1.5mm pitch
N05 G0 Z10 X0
; thread tapping with unfiltered actual positions
N10 M19 S.POS=0 M3 S1000
N20 #TURN[TAPPING_ACT_POS=1 TAPPING_N_CYCLES=0]
N30 G63 Z-150 F300 S200
N40 G63 Z10 S-200
N50 G0 X20
; tapping with filtered actual positions
N60 M19 S.POS=0 M3 S1000
N70 #TURN[TAPPING_N_CYCLES=5]
N80 G331 Z-150 K1.5 S200
N90 G332 Z10 K1.5 S200
N100 G0 X40
; tapping with command positions
N110 M19 S.POS=0 M3 S1000
N120 #TURN[TAPPING_ACT_POS=0]
N130 G63 Z-150 F300 S200
N140 G63 Z10 S-200
N160 M30
```

2.2 Functions for lathes / milling machines

These functions can be used for turning and milling work; the participating axes and the spindle axis are interpolated in the coordinated motion.

2.2.1 C axis machining

| Axis configuration in the NC channel | | |
|---|------------|----------------|
| Axis identifier | X, Y, Z, S | |
| Axis index | 0, 1, 2, 3 | |
| Kinematic structure (ID13, ID14, ID 15) | | |
| | Tool axes | Workpiece axes |
| NC axes | X, Y, Z | (S) C |

This functionality supplements the existing turning functions and permits the face and lateral surface machining of cylindrical workpieces on lathes and milling machines with revolving base. The workpiece is moved by the rotary axis or spindle (C axis) and the driven tool (e.g. a milling cutter) by the two translatory axes X (or Y) and Z. Specific settings are required in the parameters P-CHAN-00008, P-AXIS-00015 and P-AXIS-00018 for C axis machining.

Example of a configuration of a C axis in the axis parameters

```

kenngr.achs_typ    0x0002  #Path axis
or
kenngr.achs_typ    0x0004  #Spindle axis
kenngr.achs_mode   0x0204  #MODULO and CAX
  
```

Facing and lateral surface machining can be described in Cartesian coordinates.

All interpolation types (such as linear, circular or spline interpolation) are supported on the end face and lateral surface. The functionality also permits the machining of path contours running through the turning centre point. The C axis is automatically aligned on lathes.

The 2.5D tool radius compensation can be used with the familiar G commands.

The use of extended dynamic monitoring can specifically prevent dynamic axis characteristics from being exceeded with the C axis function and also with contours running close to the turning centre point.

The main axes for all machining modes are X, Y (depending on machine type), Z and C.

2.2.1.1 Exchange spindles in coordinated motion (# CAX, #CAX OFF)

This "basic mode" is required in particular for C axis machining on lathes because in this case the position-controlled spindle has to be converted into a rotary path axis (e.g "C").



Notice

C axis machining can also be executed on milling machines or machining centres which are designed with rotary workpiece fixtures (e.g. turntable). In this case, it is not necessary to select #CAX.

The three physical axes X, Y, Z and the C axis replaced in coordinated motion can be directly programmed. Linear axes are programmed in Cartesian coordinates and the C axis in angle units.

Radius and diameter programming depends on G52/G51.

Two linear axes define the main plane: ZX (G18) or YZ (G19).

Syntax:

```
#CAX [ [ [<main_spindle_name>, ] <C_axis_name> ] ]
```

<main_spindle_name> Only the main spindle name can be programmed according to P-CHAN-00053. If a spindle other than the C axis is used, it must first be declared as the main spindle (see programming example in Section [PROG// Changing the main spindle]). Otherwise, an error message is output.

<C_axis_name> Freely definable name of the C axis in the NC program. If no C axis name is programmed, the default name from P-CHAN-00010 is used.

The main plane (circular interpolation, tool radius compensation, etc.) remains the same as before activation of the C axis.

An error is generated if a command for this spindle (M3, M4, M5, etc.) is programmed although the axis is still declared as a C axis in the coordinated motion.

The C axis is deselected, i.e. the axis is released to the spindle interpolator, by the following:

Syntax:

```
#CAX OFF
```



Programing Example

C axis machining

Exchange spindles in coordinated motion

```

;...
#CAX                               ; Assuming: default C axis is "C"
G01 G90 X50 Z10 C90 F200
#CAX OFF                             ; deselect C axis mode
;...
#CAX[S, C] or #CAX[C]              ; Assuming: main spindle is "S"
G01 G90 X50 Z10 C90 F200
#CAX OFF
;...
#MAIN SPINDLE [S2]                  ; "S2" becomes new main spindle "S"
#CAX[S, C]                           ; select C axis mode
G01 G90 X50 Z10 C90 F200
;...
#CAX OFF                             ; deselect C axis mode
;...
#CAX[S3, C]; Error, "S3" is not the main spindle
    
```

2.2.1.2

Face machining (#FACE, #FACE OFF)

This mode is selected for lathes and machining centres. The desired contour on the face is programmed in millimetres or inches using a virtual Cartesian coordinate system.

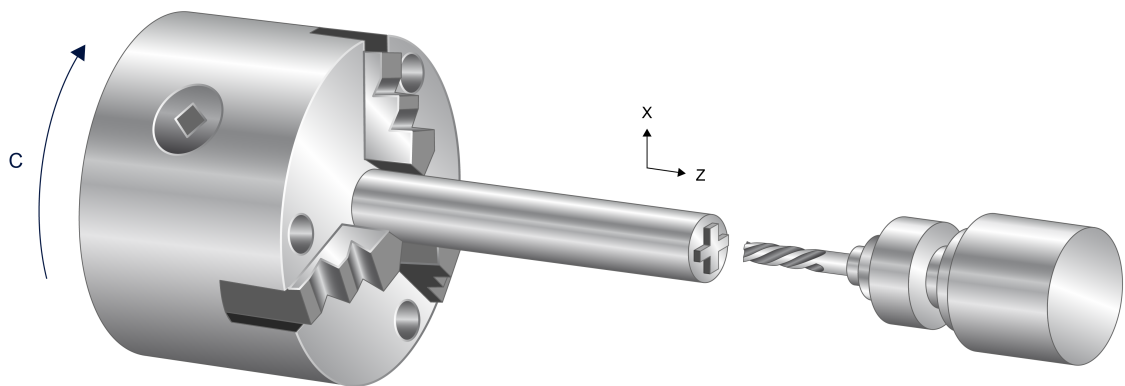


Fig. 12: Face machining



Notice

As of CNC build V3.00, the parameter P-CHAN-00262 [► 55] must be assigned with the kinematic ID used, depending on P-CHAN-00008 [► 55], in order to perform face machining applications.

- For face transformation 1 with P-CHAN-00008=1 - ID 13
- For face transformation 2 with P-CHAN-00008=2 - ID 14

The three logical axes X, Y (or C) and Z are provided to program the contour on the face in Cartesian coordinates.

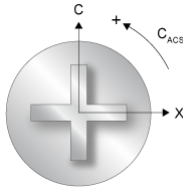


Fig. 13: Front view of face machining process

The figure below shows each of the main planes in face machining. Only the G17 plane is of technological importance.

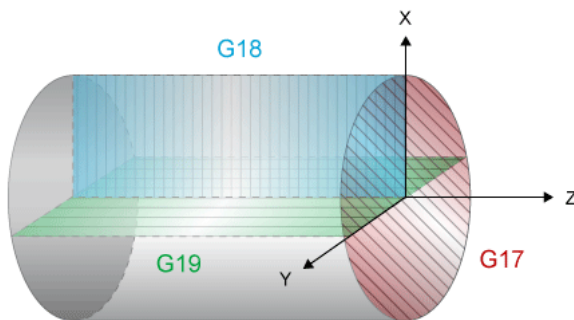


Fig. 14: Main planes of face machining

For more setting options for face machining, see [KITRA// KIN_TYP_13/14]

Syntax:

#FACE [<name of 1st main axis>, <name of 2nd main axis>]

<name of 1st main axis> Name of the first main axis according to the current main plane.

<name of 2nd main axis> Name of the second main axis according to the current main plane (virtual Cartesian axis).

When selected, the main plane (circular interpolation, tool radius compensation, etc.) is always defined by the 1st and 2nd main axes (G17). It is not permitted to change the main plane with G18, G19 while face machining is active.



Notice

Programmed tracking axes are not affected by the transformation.

This mode is deselected by:

Syntax:

#FACE OFF

Use #FACE OFF to revert to the previously active state. This means that the last active main plane is selected automatically and the last active axis offsets are restored.



Programming Example

Programming example for lathes

Example with axis name "C" for 2nd main axis

```
;...
#CAX[S, C]                ;Assuming main spindle is "S"
#FACE[X, C]              ;Select face machining
;...
G01 X40 C-30 Z50 F1000    ;Pre-position
G01 Z30                  ;Feed
G01 X10 C40              ;Travel contour
G01 Z50                  ;Retract
;...
#FACE OFF
#CAX OFF
;...
M30
```

Example with axis name "Y" for 2nd main axis.

Note: No other axis with the identical name "Y" may exist in NC channel.

```
;...
#CAX[S, Y]                ;Assuming main spindle is "S"
#FACE[X, Y]              ;Select face machining
;...
G01 X40 Y-30 Z50 F1000    ;Pre-position
G01 Z30                  ;Feed
G01 X10 Y40              ;Travel contour
G01 Z50                  ;Retract
;...
#FACE OFF
#CAX OFF
;...
M30
```



Programming Example

Programming example for machining centres

The rotary axis (workpiece axis) in the channel is "C2". It is not necessary to program the #CAX command.

```
;...
#FACE[X, C2]                ;Select face machining
;...
G01 X40 C2=-30 Z50 F1000    ;Pre-position
G01 Z30                    ;Feed
G01 X10 C2=40              ;Travel contour
G01 Z50                    ;Retract
;...
#FACE OFF
;...
M30
```

2.2.1.2.1 Face machining with 2 rotary axes (#FACE 2ROT, #FACE OFF)

Kinematic ID 203 is required for face machining with two rotary axes, The tool is then supported by the rotary axis Y and the translatory axis Z. The workpiece is aligned by the rotary axis C.

Transformation can be switched by the command #FACE 2ROT. The user programs X, Y, Z on the tool face in the Cartesian system.

The C axis must have a modulo range of 0° to 360°, see P-AXIS-00126 and P-AXIS-00127.



Notice

In order to use this face machining, the value 203 must be assigned to P-CHAN-00262 [▶ 55] for this transformation.

Syntax:

#FACE 2ROT [AX1=<name> AX2=<name> AX3=<name>] | [AXNR1=.. AXNR2=.. AXNR3=..]

| | |
|------------|--|
| AX1=<Name> | Designation of first axis |
| AX2=<Name> | Designation of second axis |
| AX3=<Name> | Designation of third axis |
| AXNR1=.. | Logical axis number P-AXIS-00016 [▶ 62] of first axis |
| AXNR2=.. | Logical axis number P-AXIS-00016 [▶ 62] of second axis |
| AXNR3=.. | Logical axis number P-AXIS-00016 [▶ 62] of third axis |

This mode is deselected by:

Syntax:

#FACE OFF

2.2.1.3 Surface machining (#CYL, #CYL OFF)

This mode can be selected for lathes and machining centres. The desired contour on the cylindrical surface is programmed in millimetres or inches using a virtual coordinate system.

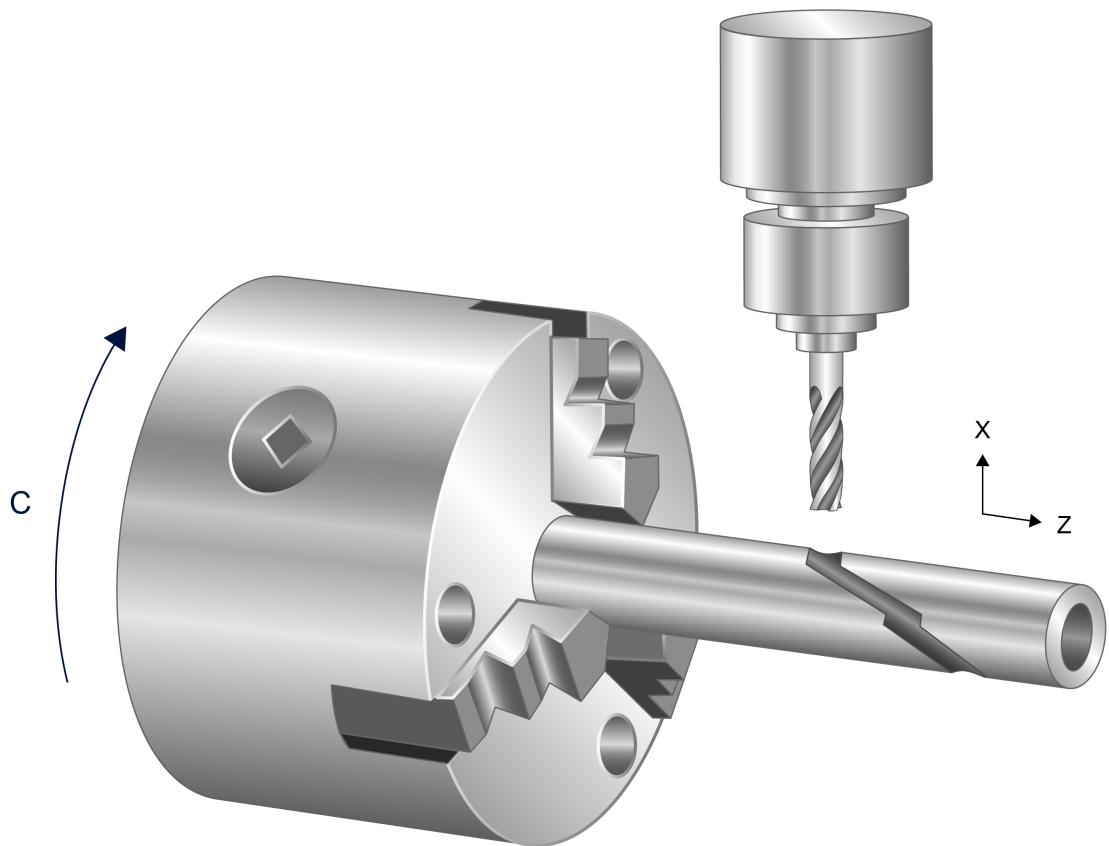


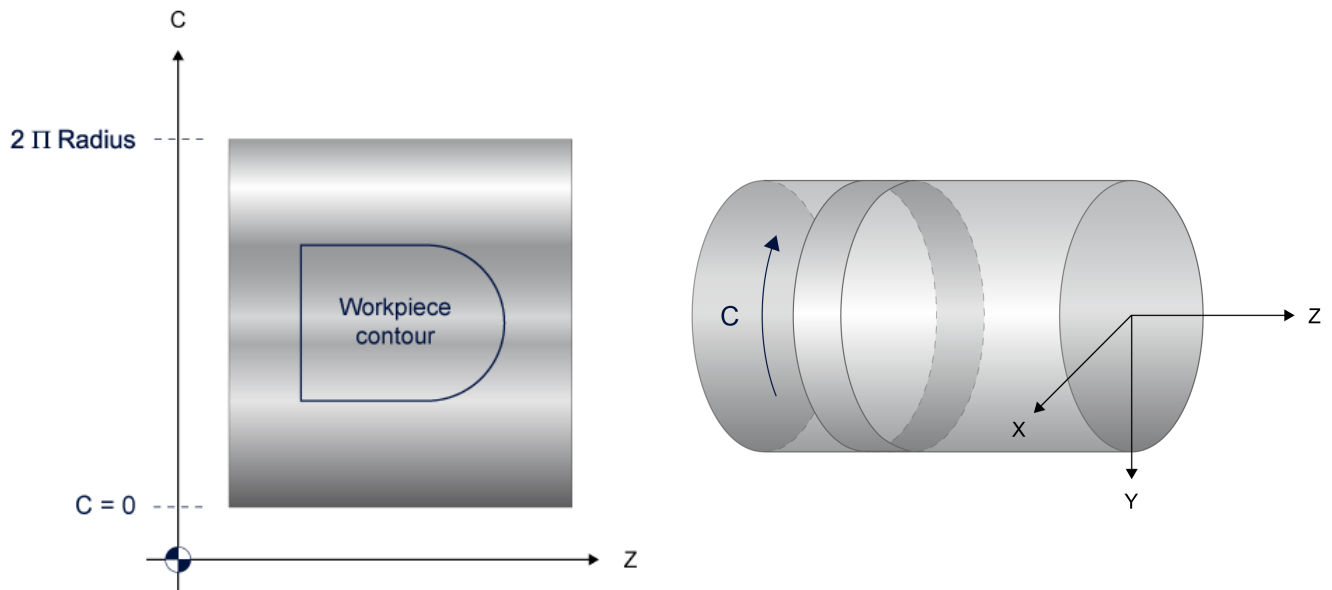
Fig. 15: Lateral surface machining



Notice

As of CNC build V3.00, the parameter P-CHAN-00262 [▶ 55] must be assigned with the value 15 for this transformation in order to perform lateral surface machining applications.

Depending on the machine type, the three logical axes X, Y, Z are provided to program the contour in Cartesian coordinates on the lateral surface. As a general rule, the Y axis is not present on lathe-only machines. The workpiece radius must also be included in the programming as reference radius R.



The main plane in lateral surface machining is formed by Z-C.

Lateral surface machining in G17

An axis configuration Z-C is formed by specifying the first and second main axes with #CYL [...]. This implicitly defines a main plane in G17. The reference radius must also be specified.

Syntax:

#CYL [<1st_main_axis_name>, <2nd main_axis_name>, <3rd_main_axis_name>..]

<1st_main_axis_name> Name of the first main axis according to the current main plane.

<2nd main_axis_name> Name of the second main axis according to the current main plane (virtual linear axis, development).

<3rd_main_axis_name>. Axis name of the third main axis according to the current main plane with specification of the reference radius in [mm, inch].



Notice

Programmed tracking axes are not affected by the transformation. It is not permitted to change the main plane with G18, G19 while lateral surface machining is active

This mode is deselected by:

Syntax:

#CYL OFF

Use #CYL OFF to revert to the previously active state. This means that the last active main plane is selected automatically and the last active axis offsets are restored.



Programming Example

Programming example for lathes, programming in G17 with Z-C

Example with axis name "C" for 2nd main axis

```
...
#CAX [S, C]           ;Assuming "S" is main spindle
G01 X60 C45 F800      ;Feed and positioning movement; X:60mm C:45°
#CYL [Z, C, X60]     ;Select lateral surface machining
G00 G90 Z0 C0        ;Z: 0mm C:0mm!
G01 C100 F500
G02 Z100 R50
G01 C0
Z0
...
#CYL OFF
#CAX OFF
M30
```

Lateral surface machining in G19

Use `#CYL LATERAL [...]` to create an axis configuration which, in combination with G19, allows programming in the virtual coordinate system C-Z. The reference radius must also be specified.

Syntax:

#CYL LATERAL [RADIUS=..]

RADIUS=.. Specify reference radius in [mm, inch].



Notice

Programmed tracking axes are not affected by the transformation. After `#CYL LATERAL`, the use of G17 or G18 is also permitted; this may be necessary for special machining cases.

This mode is deselected by:

Syntax:

#CYL OFF

Use `#CYL OFF` to deselect lateral surface machining and restore the previously active axis configuration with the associated axis offsets. The currently valid main plane remains active.



Programming Example

Programming examples for lathes, programming in G19 with C-Z

```

%cyl_lat_A
N020 G00 X0 Y0 Z0
N020 #CAX [S,C]
N030 G00 X0 Y0 Z100 C0
N040 #CYL LATERAL [RADIUS=35] ;Deselect lateral surface machining
N060 G19 ;Select G19 plane
N070 G01 G90 Z0 C0 F5000
N080 G01 G90 X10 F5000

N090 $FOR P2=1, 5, 1
N100 P3=P2*4
N110 P4=P3+2
N120 G01 G91 C-P3
N130 ZP3
N140 C[2*P3]
N150 Z-P3
N160 G90 C0
N170 G91 ZP4
N180 $ENDFOR

N190 $FOR P2=1, 5, 1
N200 P3=P2*4
N210 P4=P3*2+2
N220 G90 G02 KP3
N230 G91 G01 ZP4
N240 $ENDFOR

N270 #CYL OFF
N280 #CAX OFF
N290 M30
    
```

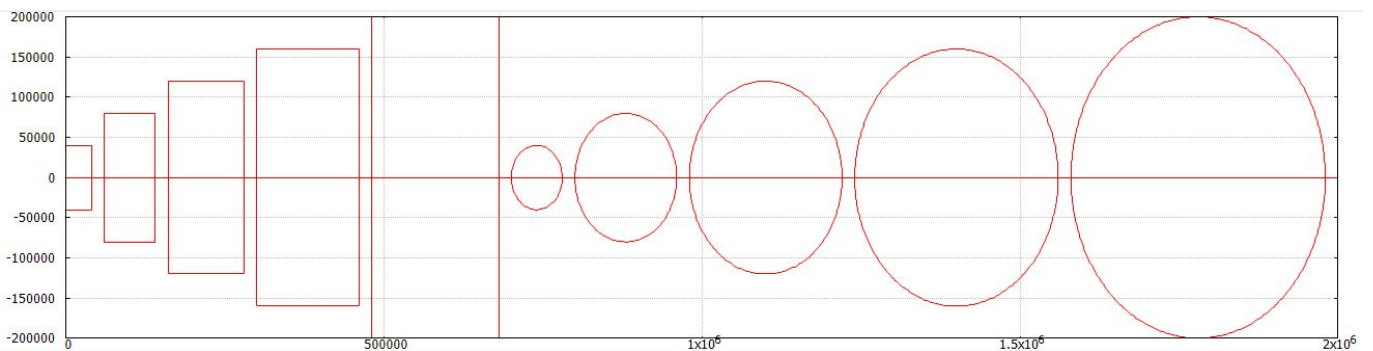


Fig. 16: Example 1 for #CAX LATERAL with G19

```
%cyl_lat_B
N020 G00 F2000 X0 Y0 Z0
N030 #CAX [S, C]
N040 #CYL LATERAL [RADIUS=20]
N060 G19
N070 G01 F1000 Z0 C0 X0 G161
N080 G02 J30 K0 C60 F2000
N090 G02 J30 K0 C0

N100 G02 J0 K30 Z60
N110 G02 J0 K30 Z0

N120 G03 J-30 K0 C-60
N130 G03 J-30 K0 C0

N140 G03 J0 K-30 Z-60
N150 G03 J0 K-30 Z0

N180 #CYL OFF
N190 #CAX OFF
N210 M30
```

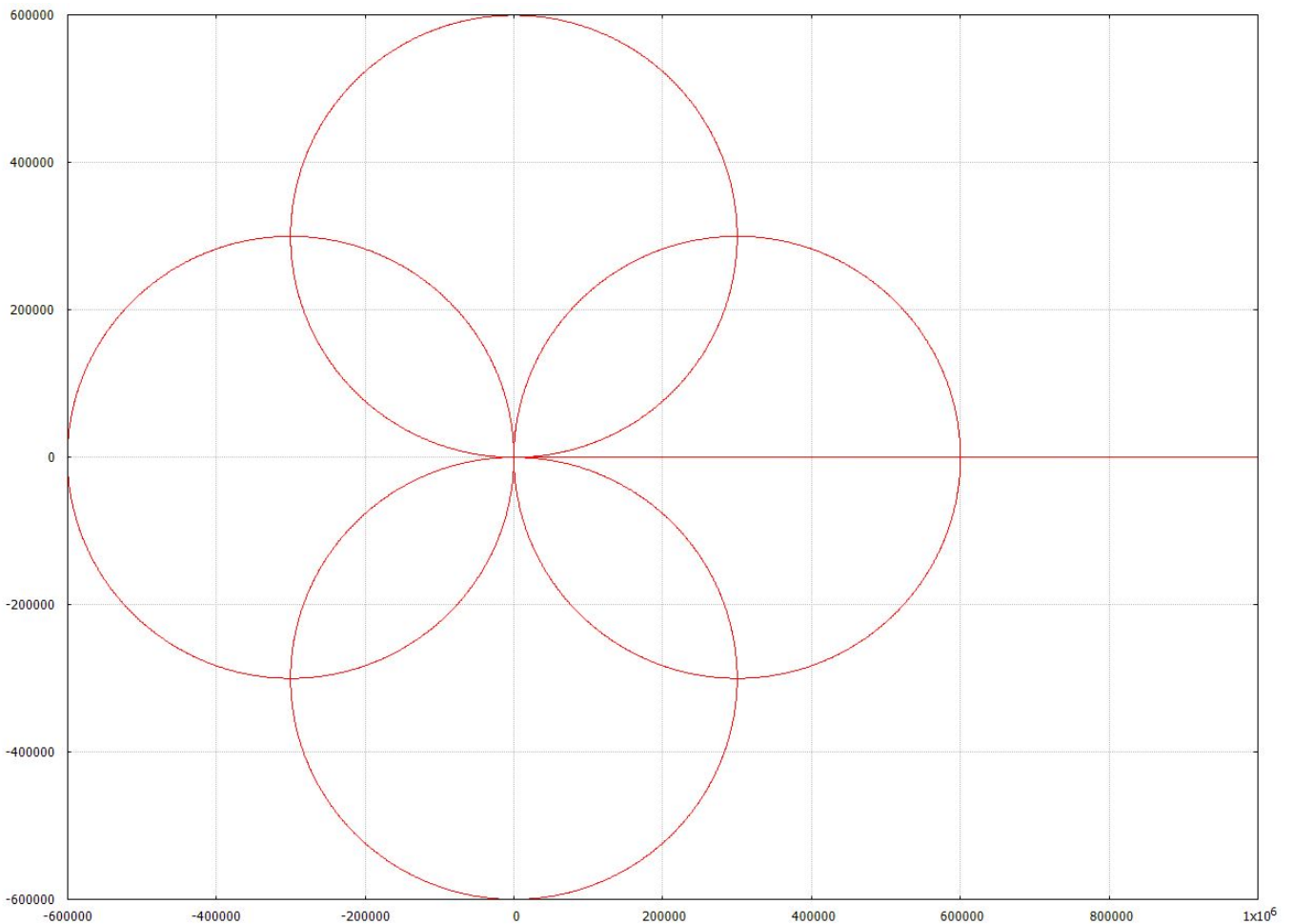


Fig. 17: Example 2 for #CYL LATERAL with G19

2.2.1.3.1 Lateral surface machining with 2 rotary axes (#CYL 2ROT, #CYL OFF)

Turning work in the Cartesian system. The tool is supported by the translatory axes X, Z and the rotary axis Y. The workpiece is aligned by the rotary axis C.

Transformation can be switched by the command #CYL 2ROT. The user programs X, Y, Z in the Cartesian system. In addition, the dimension C of the tool angle is programmed in the X-Y plane. When C=0, the tool is parallel to X and vertical on Y.



Notice

In order to use this lateral surface machining, the value 202 must be assigned to P-CHAN-00262 [▶ 55] for this transformation.

The kinematic is available in two variants.

1. In the LEFT variant (HD10 = 0) the C axis is located to the left of the Y axis. The Y axis points to the left in zero position. When transformation is selected, the X axis must be located to the right of the C axis.
2. In the RIGHT variant (HD10 = 1) the C axis is located to the right of the Y axis. The Y axis points to the right in zero position. When transformation is selected, the X axis must be located to the left of the C axis.

The C axis must have a modulo range of 0° to 360°, see P-AXIS-00126 and P-AXIS-00127.

Syntax:

#CYL 2ROT [AX1=<name> AX2=<name> AX3=<name>] | [AXNR1=.. AXNR2=.. AXNR3=..]

| | |
|------------|--|
| AX1=<Name> | Designation of first axis |
| AX2=<Name> | Designation of second axis |
| AX3=<Name> | Designation of third axis |
| AXNR1=.. | Logical axis number Axis parameter [▶ 62] of first axis |
| AXNR2=.. | Logical axis number Axis parameter [▶ 62] of second axis |
| AXNR3=.. | Logical axis number Axis parameter [▶ 62] of third axis |

This mode is deselected by:

Syntax:

#CYL OFF

3 Parameter

3.1 Overview

| Constant | Description |
|------------------|--|
| SLOPE_VB_MAX | Maximum axis speed that can be parameterised |
| ACHS_NAME_LENGTH | Maximum length of the axis designation |

| ID | Parameter | Description |
|--------------|----------------------------|--|
| P-CHAN-00082 | spdl_anzahl | Number of spindles in the channel |
| P-CHAN-00036 | log_achs_nr | Spindle axis number |
| P-CHAN-00007 | bezeichnung | Spindle designation |
| P-CHAN-00010 | default_ax_name_of_spindle | Name of the spindle as channel axis |
| P-CHAN-00043 | m19_synch | Synchronisation type of the M19 function |
| P-CHAN-00045 | m3_synch | Synchronisation type of the M03 function |
| P-CHAN-00047 | m4_synch | Synchronisation type of the M04 function |
| P-CHAN-00049 | m5_synch | Synchronisation type of the M05 function |
| P-CHAN-00081 | s_synch | Synchronisation method of the S function |
| P-CHAN-00051 | main_spindle_ax_nr | Definition of Main Spindle |
| P-CHAN-00052 | main_spindle_gear_change | Enabling gear changes |
| P-CHAN-00053 | main_spindle_name | Main spindle designation |
| P-CHAN-00074 | range_way | Search direction in the speed range table |
| P-CHAN-00004 | autom_range | Automatic gear speed change |
| P-CHAN-00058 | range_table[j].min_speed | Lower limit of speed ranges |
| P-CHAN-00055 | range_table[j].max_speed | Upper limit of speed ranges |
| P-CHAN-00008 | cax_face_id | Face machining variant (turning/milling) |
| P-CHAN-00094 | kinematik[i].param[j] | Kinematic offsets for face/lateral surface machining up to Build V3.00 |
| P-CHAN-00262 | trafo[j].id | Kinematics ID of lateral surface machining |
| P-CHAN-00263 | trafo[j].param[k] | Kinematic offsets for face/lateral surface machining as of Build V3.00 |

| ID | Parameter | Description |
|--------------|-----------------------------|--|
| P-CHAN-00761 | tapping.use_actual_position | Tapping with actual positions of the spindle |
| P-CHAN-00762 | tapping.n_cycles | Number of filter cycles to filter actual spindle positions |

| ID | Parameter | Description |
|--------------|-----------------|--|
| P-AXIS-00015 | achs_mode | Axis mode |
| P-AXIS-00016 | achs_nr | axis number |
| P-AXIS-00018 | achs_typ | Axis type |
| P-AXIS-00058 | durchm_prog_abs | Diameter programming (G51) at G90. |
| P-AXIS-00059 | durchm_prog_rel | Diameter programming (G51) at G91. |
| P-AXIS-00220 | vb_regelgrenze | Limit velocity of the measuring system |
| P-AXIS-00216 | vb_min_null | Limit value for speed 0 |

3.2 Description

3.2.1 Channel parameters

Overview

This section describes the channel-specific parameters for configuring turning functions and rotary spindles.

The spindle configuration defined in the channel parameter list is the default assignment which is provided after the controller is started up.

| P-CHAN-00761 | Tapping with actual positions of the spindle |
|---------------|--|
| Description | An additional function for tapping can be enabled to take into account the actual spindle speed. The linear axes are then coupled to the actual spindle position. This also permits tapping when the spindle speed drops due to the load. |
| Parameter | tapping.use_actual_position |
| Data type | BOOLEAN |
| Data range | 0: The spindle is coupled to the command positions of the linear axes. 1: The linear axes are coupled to the actual spindle positions. |
| Dimension | --- |
| Default value | 0 |
| Remarks | Parameter available as of V3.1.3080.04 |

| P-CHAN-00762 | Number of filter cycles to filter actual spindle positions |
|---------------------|--|
| Description | The actual spindle positions may be noisy under certain circumstances. This parameter activates a filter to smooth the actual positions, The parameter specifies the number of filter smoothing cycles. The value 0 deactivates the filter. |
| Parameter | tapping.n_cycles |
| Data type | UNS16 |
| Data range | $0 \leq n_cycles \leq 20$ |
| Dimension | --- |
| Default value | 0 |
| Remarks | P-CHAN-00762 only acts when tapping with actual spindle positions is active (P-CHAN-00761 [▶ 48]). Parameter available as of V3.1.3080.04 |

3.2.1.1 Spindle

| P-CHAN-00082 | Number of configured spindles in NC channel |
|---------------------|---|
| Description | This element specifies the total number of existing position-controlled and speed-controlled spindles. The number of spindles must be identical with the entered spindles (spindel[i].*). |
| Parameter | spdl_anzahl |
| Data type | UNS16 |
| Data range | $0 \leq spdl_anzahl \leq 6$ (application-specific) |
| Dimension | ---- |
| Default value | 0 |
| Remarks | Parameterisation example: A position-controlled and a speed-controlled spindle are to be configured. <i>spdl_anzahl 2</i> |

| | |
|---------------------|--|
| P-CHAN-00010 | Spindle name within a path compound |
| Description | If a spindle axis is changed with specific machining modes (e.g. C axis mode) in the path compound, it can be addressed by this default name (e.g. C1). |
| Parameter | <code>default_ax_name_of_spindle</code> |
| Data type | STRING |
| Data range | Maximum 16 characters (length of spindle designation, application-specific) |
| Dimension | ---- |
| Default value | * |
| Remarks | <p>The designation of spindles in the path compound must start with the letters A, B, C, U, V, W, X, Y, Z or Q. After that, all letters and digits are possible. The axis designation must be unique. It may not be identical with the configured name of a channel axis (P-CHAN-00006).</p> <p>Parameterisation example: The C axis receives the designation C1.</p> <p><code>default_ax_name_of_spindle C1</code></p> <p>* Note: The default value of variables is a blank string.</p> |

| | |
|---------------------|---|
| P-CHAN-00051 | Logical axis number of the main spindle in the NC channel |
| Description | This parameter assigns the definition of the main spindle. The logical axis number of one of the spindles which is configured in the channel parameters list is entered here. After the controller starts up, this spindle becomes the main spindle. However, any other spindle in the system can be declared to be the main spindle using a command in the part program (<code>#MAIN SPINDLE [PROG]</code>). |
| Parameter | <code>main_spindle_ax_nr</code> |
| Data type | UNS16 |
| Data range | 1 ... MAX(UNS16) |
| Dimension | ---- |
| Default value | 0 |
| Remarks | <p>Parameterisation example: The spindle with logical axis number 6 is the main spindle.</p> <p><code>main_spindle_ax_nr 6</code></p> |

| | | |
|---------------------|---|--|
| P-CHAN-00053 | Designation of the main spindle in the NC channel | |
| Description | Besides the logical axis number, a name must be assigned to the main spindle by which it can be addressed in the subroutine. This parameter therefore assigns an axis name to the main spindle. The axis name is freely selectable, but the first character must be an 'S'. | |
| Parameter | main_spindle_name | |
| Data type | STRING | |
| Data range | Maximum 16 characters (length of spindle designation, application-specific) | |
| Dimension | ---- | |
| Default value | * | |
| Remarks | <p>The designation of the main spindle cannot be changed in the subroutine. However, if the main spindle is changed using #MAIN SPINDLE (see [PROG]), the new main spindle is assigned.</p> <p>Parameterisation example: The main spindle (logical axis number 6) is programmed in the subroutine with the name 'S'.</p> <pre>main_spindle_ax_nr 6 main_spindle_name S</pre> <p>* Note: The default value of variables is a blank string.</p> | |

| | |
|---------------------|---|
| P-CHAN-00036 | Logical axis number of a spindle in NC channel |
| Description | <p>The logical axis number is entered in this parameter. The logical axis name is unique throughout the entire system. The logical axis number assigns the spindle name in the NC program to the axis data (see axis parameters lists in [AXIS]). Therefore only logical numbers make sense if they are known to the NC program.</p> <p>The logical axis number "0" is not permitted.</p> |
| Parameter | spindel[i].log_achs_nr |
| Data type | UNS16 |
| Data range | 1... MAX(UNS16) |
| Dimension | ---- |
| Default value | - |
| Remarks | A logical axis number may not be assigned several times. A logical axis number may not be simultaneously configured as path axis and spindle. If this is the case, the plausibility check of the channel parameters generates an error message at start-up. |

| | |
|---------------------|--|
| P-CHAN-00007 | Name of a spindle in the NC channel |
| Description | This parameter defines the default name to address the spindle in the NC program. Please note that as long as a spindle is the main spindle, it can only be programmed using the main spindle name. The spindle name is a string. |
| Parameter | spindel[i].bezeichnung |
| Data type | STRING |
| Data range | Maximum 16 characters (length of spindle designation, application-specific) |
| Dimension | ---- |
| Default value | * |
| Remarks | <p>The spindle names must start with the letter 'S'. After that, all letters and digits are possible. Spindle names must be unique.</p> <p>Parameterisation example: Configuration of a 1-channel system with 3 spindles. After start-up, spindle 'S1' with logical axis number 6 is the main spindle. It is addressed by the spindle name 'S'. The spindles with logical axis numbers 11 and 30 are programmed by their default names 'S2' and 'S3'.</p> <pre> spdl_anzahl 3 : main_spindle_ax_nr 6-> -> ->- main_spindle_name S ->- / # / / spindel[0].bezeichnung S1-<- / spindel[0].log_achs_nr 6-< -< -<- : spindel[1].bezeichnung S2 spindel[1].log_achs_nr 11 : spindel[2].bezeichnung S3 spindel[2].log_achs_nr 30 * Note: The default value of variables is a blank string. </pre> |

| | |
|---------------------|---|
| P-CHAN-00052 | Enable mechanical gear change of main spindle |
| Description | This parameter enables or disables gear changes for the main spindle. |
| Parameter | main_spindle_gear_change |
| Data type | BOOLEAN |
| Data range | 0: Spindle gear changes disabled for the main spindle 1: Spindle gear changes enabled for the main spindle |
| Dimension | ---- |
| Default value | 0 |
| Remarks | The M functions to select the gear speeds of the main spindle M40–45 are activated by the parameter P-CHAN-00052 in the channel parameter list. The M functions M40–45 can be freely used if gear changes are disabled. |

| P-CHAN-00074 | Direction of range selection for spindle gear change |
|---------------------|--|
| Description | This parameter defines whether the lower or the higher gear range is selected when speed ranges overlap. If 'range_way' = 0 the search starts from the lowest speed range, if 'range_way' > 0 from the highest. The correct speed (gear) range is the one where the programmed spindle speed is first found. |
| Parameter | spindel[i].range_way |
| Data type | UNS16 |
| Data range | $0 \leq \text{range_way} < \text{MAX}(\text{UNS16})$ |
| Dimension | ---- |
| Default value | 0 |
| Remarks | Parameterisation example: The search starts from the lowest speed range. <i>spindel[0].range_way 0 (from bottom to top)</i> |

| P-CHAN-00004 | Automatic range selection for spindle gear change |
|---------------------|--|
| Description | If the spindle gear range is to be automatically determined by the NC kernel, this parameter must be set to 1. In this case the M functions M40 to M45 need not be programmed. This means that the correct gear range is determined implicitly by the programmed speed (S word). |
| Parameter | spindel[i].autom_range |
| Data type | BOOLEAN |
| Data range | 0/1 |
| Dimension | ---- |
| Default value | 0 |
| Remarks | Parameterisation example: The automatic range selection is enabled. <i>spindel[0].autom_range 1</i> |

| | |
|---------------------|--|
| P-CHAN-00058 | Minimum spindle speed of a speed range (spindle gear change) |
| Description | The speed ranges of a spindle may be defined with or without overlap. If one range is not used, the corresponding values must be set to zero in the table. |
| Parameter | spindel[i].range_table[j].min_speed |
| Data type | UNS16 |
| Data range | $0 \leq \text{min_speed} \leq \text{MAX}(\text{UNS16})$ |
| Dimension | rpm |
| Default value | 0 |
| Remarks | <p>Parameterisation example: Definition of a speed range table for 6 ranges. Only the first four ranges are used.</p> <pre> spindel[0].range_table[0].min_speed 50 spindel[0].range_table[0].max_speed 560 spindel[0].range_table[1].min_speed 400 spindel[0].range_table[1].max_speed 800 spindel[0].range_table[2].min_speed 700 spindel[0].range_table[2].max_speed 3360 spindel[0].range_table[3].min_speed 3361 spindel[0].range_table[3].max_speed 4000 spindel[0].range_table[4].min_speed 0 spindel[0].range_table[4].max_speed 0 spindel[0].range_table[5].min_speed 0 spindel[0].range_table[5].max_speed 0 </pre> |

| | |
|---------------------|--|
| P-CHAN-00055 | Maximum spindle speed of a speed range (spindle gear change) |
| Description | The speed ranges of a spindle may be defined with or without overlap. If one range is not used, the corresponding values must be set to zero in the table. |
| Parameter | spindel[i].range_table[j].max_speed |
| Data type | UNS16 |
| Data range | $0 \leq \text{max_speed} \leq \text{MAX}(\text{UNS16})$ |
| Dimension | rpm |
| Default value | 0 |
| Remarks | <p>Parameterisation example: Definition of a speed range table for 6 ranges. Only the first four ranges are used.</p> <pre> spindel[0].range_table[0].min_speed 50 spindel[0].range_table[0].max_speed 560 spindel[0].range_table[1].min_speed 400 spindel[0].range_table[1].max_speed 800 spindel[0].range_table[2].min_speed 700 spindel[0].range_table[2].max_speed 3360 spindel[0].range_table[3].min_speed 3361 spindel[0].range_table[3].max_speed 4000 spindel[0].range_table[4].min_speed 0 spindel[0].range_table[4].max_speed 0 spindel[0].range_table[5].min_speed 0 spindel[0].range_table[5].max_speed 0 </pre> |

3.2.1.2 Kinematics

| | |
|---------------------|---|
| P-CHAN-00008 | Machine ID with C axis face machining |
| Description | This parameter defines the type of machine used for face machining. |
| Parameter | cax_face_id |
| Data type | UNS16 |
| Data range | 1: Lathe (automatic orientation of the rotary axis in the centre of rotation) 2: Milling machines (no orientation) |
| Dimension | ---- |
| Default value | 0 |
| Remarks | Parameterisation example: Face machining takes place on a milling machine. <i>cax_face_id 2</i> |

As of CNC Build V3.00

| | |
|---------------------|--|
| P-CHAN-00262 | Define kinematic ID for transformations |
| Description | The kinematic ID identifies the related transformation as an element of the data set of kinematic parameters. The definition can be made for single-step, multi-step and PCS transformations. |
| Parameter | trafo[j].id kin_step[i].trafo[j].id (multi-step transformations) trafo_pcs[i].id (PCS transformation *) |
| Data type | UNS16 |
| Data range | 1 ... MAX(UNS16) |
| Dimension | ---- |
| Default value | 0 |
| Remarks | Parameter syntax as of V300 and higher *The PCS transformation function is available as of V3.1.3110. |

| | |
|---------------------|---|
| P-CHAN-00263 | Define kinematic parameters for multi-step transformations |
| Description | The specific kinematic offsets are entered in this structure for each transformation. You can specify offsets for single-level, multilevel transformations and PCS transformations. |
| Parameter | trafo[j].param[k] or where k = 0 to 73 (maximum number of kinematic parameters) kin_step[i].trafo[j].param[k] (multi-step transformations) trafo_pcs[i].param[k] (PCS transformation *) |
| Data type | REAL64 |
| Data range | ---- |
| Dimension | 0.1 µm or 0.0001 inch |
| Default value | 0 |
| Remarks | <p>Kinematic parameters can also be entered in the tool data list P-TOOL-00009 (they are then relevant only when a tool is selected, independent of the kinematics).</p> <p>If a kinematic parameter is assigned in both lists, the specified values are added in the NC. This is only valid for transformation step 1.</p> <p>No additional kinematic parameters can be entered in the tool data for transformation step 2.</p> <p>For further details on the parameterisation of a kinematic transformation, see [KITRA] and [PROG].</p> <p>(Parameter syntax as of V300)</p> <p>*The PCS transformation function is available as of V3.1.3110.</p> |

For CNC Builds < V3.00

| | |
|---------------------|--|
| P-CHAN-00094 | Define kinematic parameters |
| Description | The specific kinematic offsets are entered in this structure for each transformation. |
| Parameter | kinematik[i].param[j] where j = 0... 74 (maximum number of kinematic parameters, application-specific, syntax as of V2.10.1501) |
| Data type | REAL64 |
| Data range | ---- |
| Dimension | 0.1µm or 0.0001° (for offsets) |
| Default value | 0 |
| Remarks | <p>Parametrising kinematics for CNC Builds V2.11.2xxx</p> <p><i>kinematik[i].wz_kopf_ersatz[j]</i> (syntax up to V260)</p> <p>Kinematic parameters can also be entered in the tool data list P-TOOL-00009 (they are then relevant only when a tool is selected independent on the kinematics). If a kinematic parameter is assigned in both lists, the specified values are added in the NC.</p> <p>For more details on parameterising kinematic transformation and 5-axis machining, see [KITRA] and [PROG].</p> <p>Parameterisation example: Offset values are specified for kinematics 1, 2 and 5. The kinematic with ID 2 is the default kinematic.</p> <pre> kinematik_id 2 Default kinematic: 2 # kinematik[1].param[0] 1088000 kinematik[1].param[1] 1987000 kinematik[1].param[2] 342000 # kinematik[2].param[0] 1538000 kinematik[2].param[1] 25000 kinematik[2].param[2] 0 kinematik[2].param[5] 1800000 # kinematik[5].param[0] 1487000 kinematik[5].param[1] 25000 </pre> |

3.2.1.2.1 Tool offsets

The commands #FACE and #CYL result in the implicit selection of kinematics. For this reason, neither a kinematic ID requires a #KIN ID [...] nor transformation activation with #TRAFO ON.

Tool offsets for face machining

Face machining supports 2 machine types (lathe/milling machine). The corresponding tool offsets must be entered in the channel parameters in the assigned offset data of the kinematic IDs 13 and 14. Alternatively, this can also be executed in the tool data.

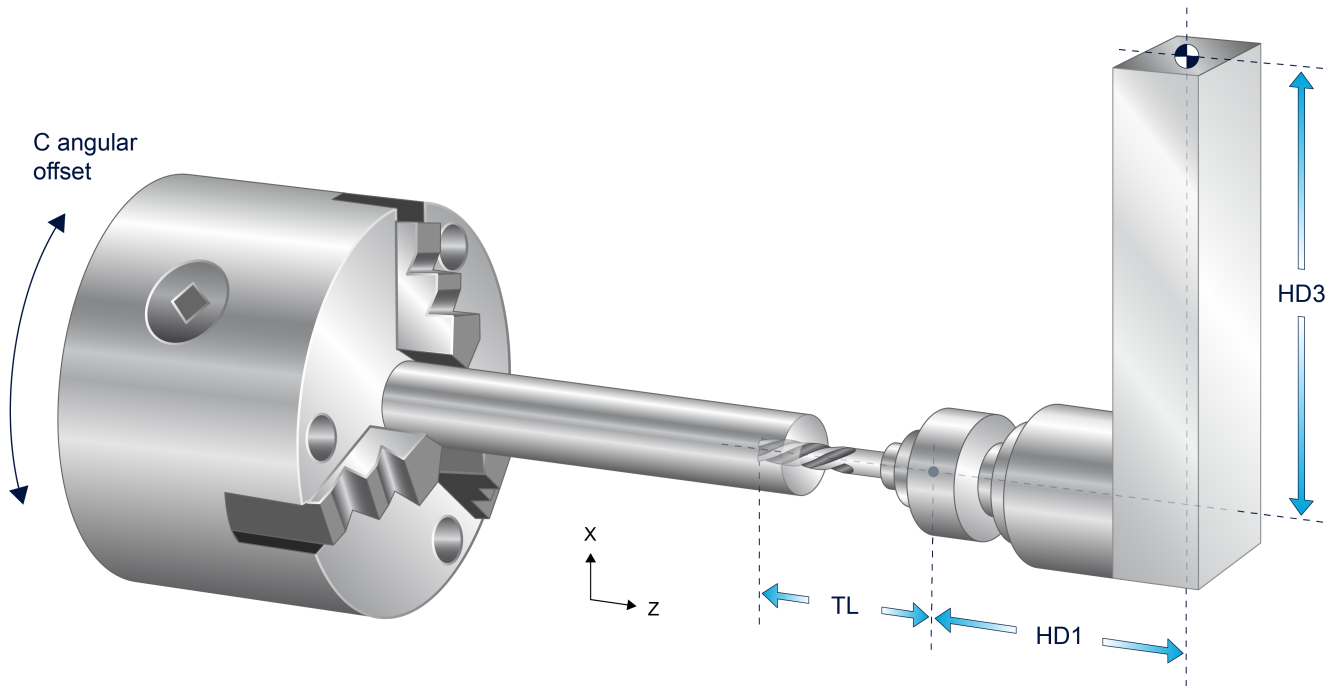


Fig. 18: Tool offsets for face machining



Example

Examples of entries in channel parameters

for CNC Builds as of V3.00

FACE[], Face machining on a lathe (KIN-ID 13):

```
trafo[0].id                13
trafo[0].param[0]         1080000   Z offset [0.1µm]
trafo[0].param[1]         0          C angular offset [10-4°]
trafo[0].param[2]         900000    X offset [0.1µm]
```

FACE[], Face machining on a milling machine (KIN-ID 14):

```
trafo[1].id                14
trafo[0].param[0]         1080000   Z offset [0.1µm]
trafo[0].param[1]         0          C angular offset [10-4°]
trafo[1].param[2]         900000    X offset [0.1µm]
```

CNC Builds < V3.00

FACE[], Face machining on a lathe (KIN-ID 13):

```
kinematik[13].param[0]    1080000   Z offset [0.1µm]
kinematik[13].param[1]    0          C angular offset [10-4°]
kinematik[13].param[2]    900000    X offset [0.1µm]
```

FACE[], Face machining on a milling machine (KIN-ID 14):

```
kinematik[14].param[0]    1080000   Z offset [0.1µm]
kinematik[14].param[1]    0          C angular offset [10-4°]
kinematik[14].param[2]    900000    X offset [0.1µm]
```

Tool offsets for lateral surface machining

Lateral surface machining implicitly executes the selection of the kinematic with ID 15.

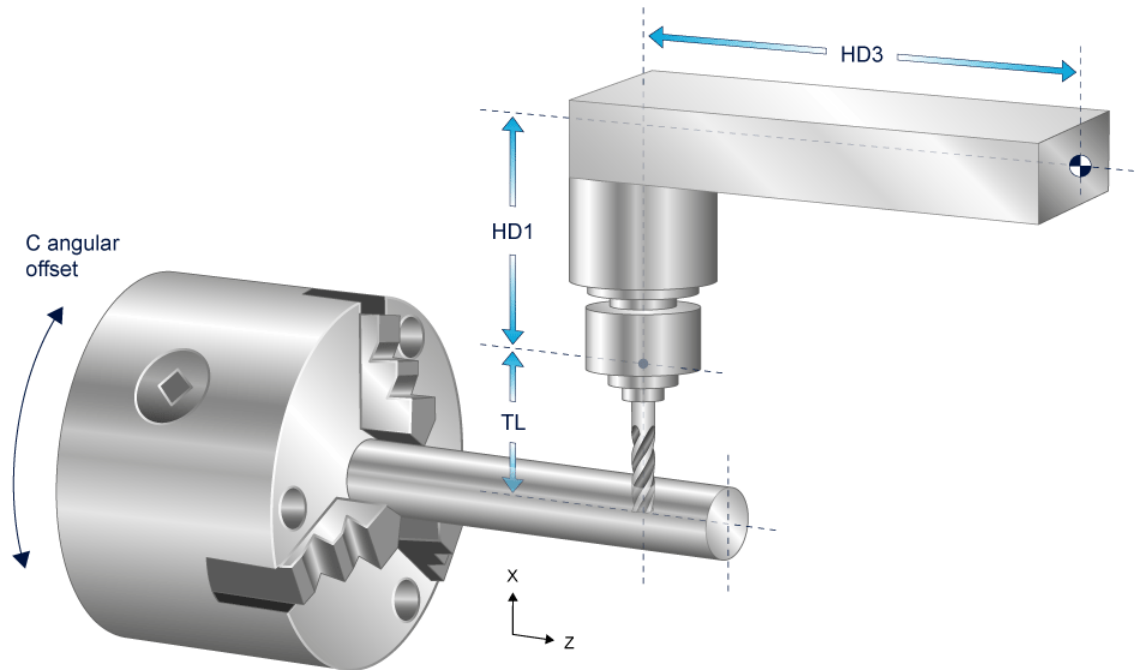


Fig. 19: Tool offsets for lateral surface machining

#CYCL[], Lateral surface machining lathe (KIN-ID 15):

CNC Builds as of V3.00

| | | |
|-------------------|---------|---------------------------------------|
| trafo[0].id | 15 | |
| trafo[0].param[0] | 700000 | X offset [0.1µm] |
| trafo[0].param[0] | 0 | C angular offset [10 ⁻⁴ °] |
| trafo[2].param[0] | 1200000 | Z offset [0.1µm] |

CNC Builds < V3.00

| | | |
|------------------------|---------|---------------------------------------|
| kinematik[15].param[0] | 700000 | X offset [0.1µm] |
| kinematik[15].param[1] | 0 | C angular offset [10 ⁻⁴ °] |
| kinematik[15].param[2] | 1200000 | Z offset [0.1µm] |

3.2.2 Axis parameter

Overview

The specific parameters for spindle axes and linear axes are described here. Refer to the documentation [AXIS] for details of further parameters available for setting axes.

Operation mode settings (P-AXIS-00015) for spindle axes

- 0x4: A modulo calculation always takes place after the destination position has been reached. Regardless of the operation mode selected for rotary axes, a modulo calculation is always executed in the position controller. In this way, modulo circle compensation can be executed if required.
- 0x100: For a spindle an automatic homing before positioning the spindle can be pre-vented. This is, of course, relevant only if the axis is not referenced. The function is drive-dependent.
- 0x200: Axis for kinematic "C axis" transformation

Operation mode settings (P-AXIS-00015) for path axes

- 0x1: Linear axis
- 0x40: Face turning axis
- 0x80: Longitudinal turning axis

| P-AXIS-00015 | Axis mode | |
|---------------|---|-----------|
| Description | Axes can be traversed in different operating modes. | |
| Parameter | kenngr.achs_mode | |
| Data type | UNS32 | |
| Data range | 0x00000001 - 0x10000000 | |
| Axis types | T, R, S | |
| Dimension | T: ---- | R,S: ---- |
| Default value | 0x00000001 | |
| Drive types | ---- | |
| Remarks | | |

| | | |
|---------------------|--|-----------|
| P-AXIS-00016 | Logical axis number | |
| Description | The logical axis number is a system-wide unique identifier for each axis. The entire management of axis data in the NC kernel takes place using the logical axis number. | |
| Parameter | kopf.achs_nr | |
| Data type | UNS16 | |
| Data range | 0 < achs_nr < MAX(UNS16) | |
| Axis types | T, R, S | |
| Dimension | T: ---- | R,S: ---- |
| Default value | 1 | |
| drive types. | ---- | |
| Remarks | <p>It is not allowed to use the same logical axis number more than once. The logical axis number "0" is not allowed.</p> <p>The assignment of an axis designation in the NC program to a logical axis (axis number) takes place in the channel parameters [CHAN].</p> <p>This entry is not adopted when the axis parameter list is updated. Updates only become effective when the controller is rebooted.</p> | |
| P-AXIS-00018 | Axis type (linear axis, rotary axes, spindle) | |
| Description | This parameter specifies the axis type of an axis. | |
| Parameter | kenngr.achs_typ | |
| Data type | STRING | |
| Data range | Linear axis (ACHSTYP_TRANSLATOR) : 0x0001 Rotary axis (ACHSTYP_ROTATOR) : 0x0002 Spindle (ACHSTYP_SPINDEL): : 0x0004 | |
| Axis types | T, R, S | |
| Dimension | T: ---- | R,S: ---- |
| Default value | ACHSTYP_TRANSLATOR | |
| Drive types | ---- | |
| Remarks | <p>Depending on the axis type that is set, special functionalities are addressed in the NC kernel.</p> <p>Examples:</p> <ul style="list-style-type: none"> - modulo calculation for rotary axes, - speed monitoring for spindles | |

| | | |
|---------------------|--|-------------|
| P-AXIS-00220 | Limiting velocity for the measurement system | |
| Description | Especially with spindles, the limit at which the measuring system supplies erroneous signals at higher rotation speeds can be exceeded. The parameter describes the velocity value at which the position controller has to switch over to open-loop controlled operation mode. | |
| Parameter | getriebe[i].vb_regelgrenze | |
| Data type | UNS32 | |
| Data range | $0 \leq vb_regelgrenze \leq \text{MAX}(\text{UNS32})$ | |
| Axis types | S | |
| Dimension | | S: 0.001°/s |
| Default value | 200000 | |
| drive types. | Simulation, Conventional, Terminal, Lightbus, Profidrive | |
| Remarks | | |

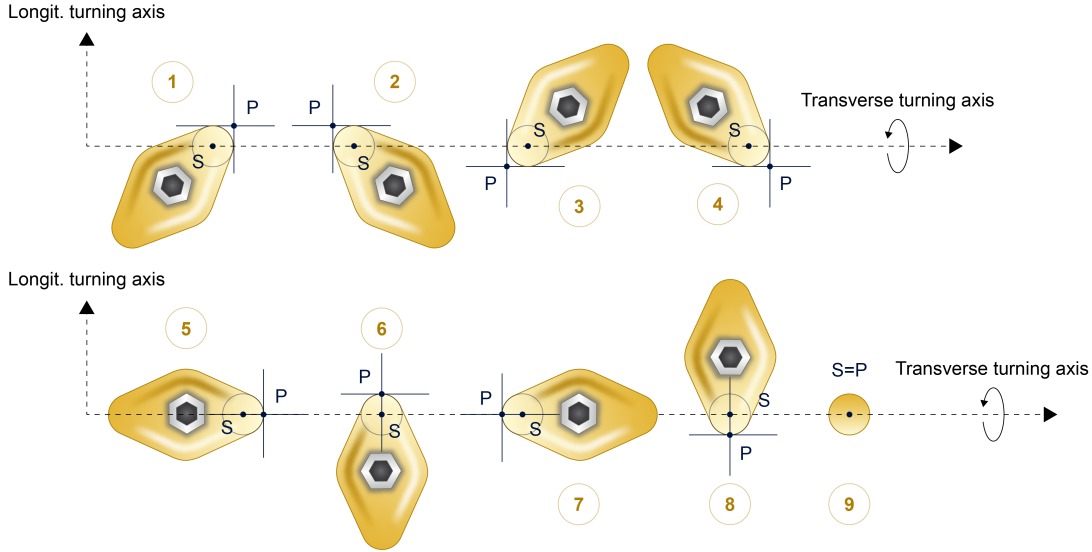
| | | |
|---------------------|--|-------------|
| P-AXIS-00216 | Limit for spindle speed 'zero' | |
| Description | Especially in the case of spindles, the barrier should be given below which rotational speed monitoring in the position controller shows the state 'speed zero'. | |
| Parameter | getriebe[i].vb_min_null | |
| Data type | UNS32 | |
| Data range | $0 \leq vb_min_null \leq \text{MAX}(\text{UNS32})$ | |
| Axis types | S | |
| Dimension | | S: 0.001°/s |
| Default value | 100 | |
| drive types. | ---- | |
| Remarks | | |

| | | |
|---------------------|--|--|
| P-AXIS-00058 | Diameter programming absolute | |
| Description | If diameter programming is to occur with active absolute programming (G90), the parameter must be set to TRUE. | |
| Parameter | kenngr.durchm_prog_abs | |
| Data type | BOOLEAN | |
| Data range | 0/1 | |
| Axis types | T | |
| Dimension | T: ---- | |
| Default value | 0 | |
| drive types. | ---- | |
| Remarks | | |

| | | |
|---------------------|---|--|
| P-AXIS-00059 | Diameter programming relative | |
| Description | If diameter programming is to occur with active incremental programming (G91), the parameter must be set to TRUE. | |
| Parameter | kenngr.durchm_prog_rel | |
| Data type | BOOLEAN | |
| Data range | 0/1 | |
| Axis types | T | |
| Dimension | T: ---- | |
| Default value | 0 | |
| drive types. | ---- | |
| Remarks | | |

3.2.3 Tool parameters

| | | |
|---------------------|---|--|
| P-TOOL-00001 | Differentiation between tool types | |
| Description | This parameter is assigned to distinguish between tool types. | |
| Parameter | wz[i].typ | |
| Data type | UNS16 | |
| Data range | 0: Milling tool 1: Turning tool 2: Grinding tool 3: Wire (erosion) | |
| Unit | ---- | |
| Default value | 0 | |
| Remarks | Parameterisation example: Tool 5 is a milling tool <i>wz[5]typ 0</i> | |

| P-TOOL-00002 | Cutter edge position |
|---------------|--|
| Description | <p>With rotary tools (P-TOOL-00001 = 1), this parameter specifies the orientation of the cutter relative to the machining plane.</p>  <p>Ident. codes 1 to 9 for orientation of the turning tool tip in the machining plane.</p> |
| Parameter | wz[i].srk_lage |
| Data type | UNS16 |
| Data range | 0 < srk_lage ≤ 9 |
| Dimension | ---- |
| Default value | 0 |
| Remarks | <p>For detailed information regarding machining with turning tools, see [PROG ▶ 12]].</p> <p>Parameterisation example: The orientation of the cutter tip of Tool 6 is described by identification code 3.</p> <pre>wz[6].typ 1 wz[6].srk_lage 3</pre> |

4 Appendix

4.1 Suggestions, corrections and the latest documentation

Did you find any errors? Do you have any suggestions or constructive criticism? Then please contact us at documentation@isg-stuttgart.de. The latest documentation is posted in our Online Help (DE/EN):



QR code link: <https://www.isg-stuttgart.de/documentation-kernel/>

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